

LECTURER NOTES

DESIGN OF STEEL STRUCTURES

**B.Tech, 6TH Semester,
Civil Engineering**

Prepared by:
Anjana Khamari
Assistant Professor in Civil Engineering



Vikash Institute of Technology, Bargarh

(Approved by AICTE, New Delhi & Affiliated to BPUT, Odisha)

Barahaguda Canal Chowk, Bargarh, Odisha-768040

www.vitbargarh.ac.in

COURSE CONTENT

Design of Steel Structure

B.Tech, 6th Semester, CE

Module I

Introduction, advantages/disadvantages of steel, structural steel, rolled steel section, various types of loads, design philosophy. Limit state design method, limit states of strength and serviceability, probabilistic basis for design Riveted, bolted and pinned connections, Welded connections- assumptions, types, design of fillet welds, intermittent fillet weld, plug and slot weld, failure of welded joints, welded joints vs bolted and riveted joints

Module II

Tension members, types, net cross-sectional area, types of failure, slenderness ratio, design of tension members, gusset plate.

Module III

Compression members, effective length, slenderness ratio, types of cross-section, classification of cross section, Design of axially loaded compression members, lacing, battening, design of column bases, and foundation bolts.

REFERENCES

Design of Steel structures

B.Tech, 6th Semester, CE

Books:

- [1] Limit State Design of Steel structures by S.K. Duggal, Mc-Graw Hill

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Design of steel structures

t 2/bb

- Types of sections
- Grades of steel
- Strength characteristics
- IS code connections
- Design of tension & compression members
- Steel roof truss, beams, column bases.

IRON1. Pure iron (non alloy)! →

- It is natural metal available directly in the earth ore.
- silvery white in colour.
- It is very soft solid such that it can be cut by knife, having high ductility.
- It is not used in any structural element since it directly reacts with oxygen & to form rust & reacts with moist air.
- It is available in Fe₂ & Fe₃ forms.

2. Pig iron! →

- Basic raw iron is called pig iron (transported in the form of bricks).
- It is also not used in any structural element since it is composed of highest carbon content (5%).
- The pig iron can be converted into structural iron by removing excess carbon content & by adding oxygen or chemicals in molten stage.

3. Cast iron! —

- It is the structural element in specified shape from molten pig iron having almost same properties of pig iron.

4. Wrought Iron! →

- Lowest carbon content (0.0-0.1%) of structural iron
- It has high ductility, easily converted in specified shape.
- Largely used to make thin wires.

5. Steel! →

- Steel is an alloy of → (Iron + carbon + chromium + copper + magnesium + nickel + silica)
- The structural elements used to resist any type of load.

Carbon content

- Pig iron → 4-5%.
- Cast iron → (2-4.5%)
- Cast steel → (>2%)
- Carbon steel (less than 2%)
- High carbon steel → (0.6-1.4%)
- medium " " → 0.25-0.6%
- Low " " → less than 0.25%
- Wrought iron - less than 0.1%
- pure " - 0%

Introduction

properties	low carbon	medium carbon	High carbon
Carbon	lower than 0.25 wt. %	In bet ⁿ 0.25 x 0.6 wt. %	In bet ⁿ 0.6 x 0.7 wt. %
Some properties	- Excellent ductility & toughness. - Weldable & machinable - Not amenable to martensite transformation	- Low ductility - These steel grades can be heat treated.	Hardest, strongest & least ductile.
Some app ⁿ	common products like Nuts, bolts, sheets, etc.	for higher strength such as in machinery, Automobiles & agricultural parts (gears, axels, connecting rods) etc.	used where strength, hardness & wear resistance is required. cutting tool (able, musical wires,

→ Steel is an alloy of Fe + Carbon

Mild steel (carbon content = 0.23%)

- when carbon is increased in steel then strength, hardness & brittleness will increase but ductility will decrease.

Stainless steel →

- Alloy of iron & chromium
- chromium is 18% & Nickel is 8%
- Young's modulus of steel $E = 2 \times 10^5 \text{ MPa}$
 $= 200 \text{ GPa}$

$$E_{\text{Aluminium}} = \frac{1}{3} E_{\text{steel}}$$

$$= 0.7 \times 10^5 \text{ MPa or } 70 \text{ GPa}$$

Density of steel :-

$$\rho = \begin{cases} \rho_{\text{steel}} = 7850 \text{ kg/m}^3 \\ \rho_{\text{Aluminium}} = \frac{\rho_{\text{steel}}}{3} = 2700 \text{ kg/m}^3 \end{cases}$$

Modulus of Rigidity (G) :-

$$G = 0.769 \times 10^5 \text{ MPa}$$

Poisson's Ratio (μ) :-

$$\mu = \frac{\text{lateral strain}}{\text{longitudinal strain}}$$

- μ for mild steel = 0.28
- In elastic range = 0.3
- In plastic " = 0.5

Deflection / Increase in length :-

$$\Delta L = \frac{PL}{AE}$$

$$(\Delta L)_{\text{mild steel}} = \frac{1}{3} (\Delta L)_{\text{Al}}$$

Thermal coefficient :-

$$\alpha_{\text{steel}} = \alpha_{\text{concrete}} = 12 \times 10^{-6} \text{ } ^\circ\text{C}^{-1}$$

$$\alpha_{\text{Al}} = 23 \times 10^{-6} \text{ } ^\circ\text{C}^{-1}$$

- steel is ductile while concrete are brittle and brittle.

Note! —

Rubber is a very brittle material, there is very little plastic deformation beyond elastic range.

Some imp. codes

IS 456 : 2000 → RCC

IS 800 : 2008 → steel (2007-ISM, 1984-WSM)

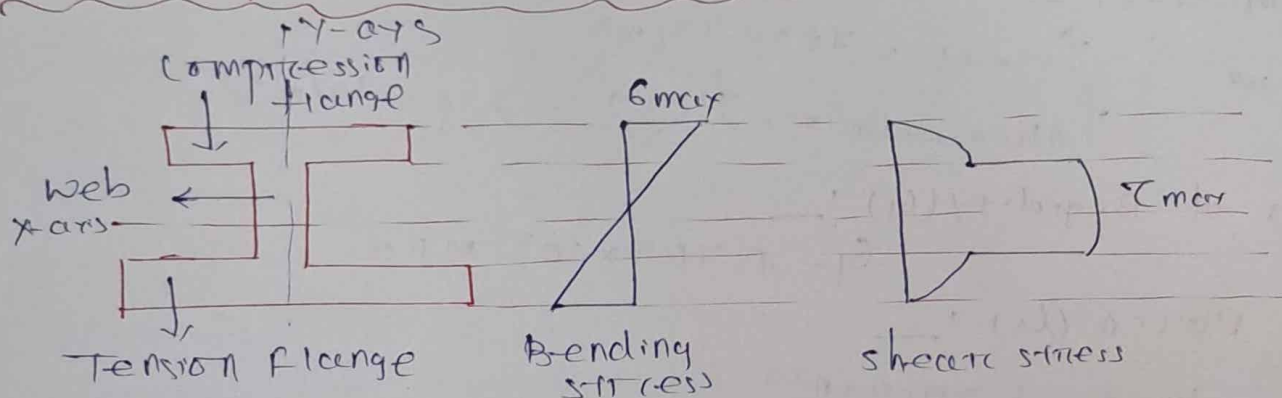
IS 1343 → Pre stress concrete

IS 10262 → Dgn. mix

IS 383 → Fine & coarse aggregate

IS 825 → Dgn. load for buildings & structures.

Standard structural steel section



→ In I-section, the web resists SF, while the flanges resist most of BM experienced by the beam.

- i) ISLB 350 —
- Indian standard light beam where overall depth = 350mm
 - maxm bending stress is resisted by flange & maxm shear stress by web.
 - Generally used in roof beam.

- i) ISMB —
- Indian standard medium flange beam generally used in floor beams.
 - High moment of inertia about x-axis, so lateral buckling occurs about y-axis.

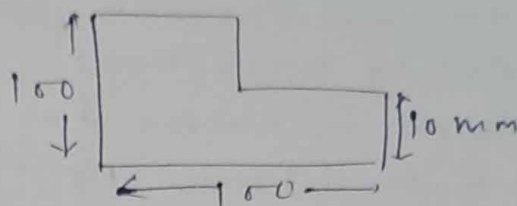
- iii) ISWB : — Indian standard wide flange beam generally used in column.
- High moment of inertia about y-axis, so they have bending strength about y-axis.
- iv) ISJB : — IS junior beam
- v) ISHB : — " Heavy "

Angle section

i) equal Angle secⁿ : —

ISA - 100 x 100 x 10

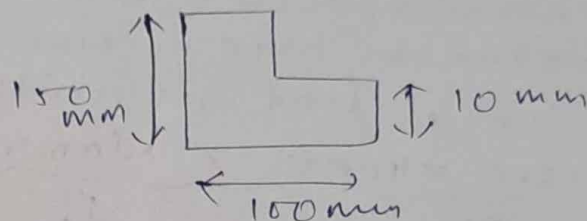
Both legs are same
thickness of angle secⁿ



ii) unequal angle secⁿ : —

ISA - 150 x 100 x 10

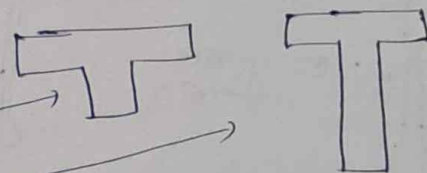
different leg
thickness



T-secⁿ : —

i) ISH T - IS wide flange T secⁿ

ii) ISST - IS standard long legged T secⁿ



channel secⁿ : —

— they are used as purlins or columns

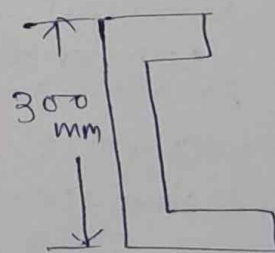
(purlin is a beam in a roof truss which supports the roof covering material).

i) ISJC - IS junior channel secⁿ

ii) ISLC - IS light " "

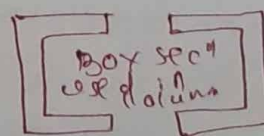
iii) ISMC 300 - IS medium " "

iv) ISSC - IS special " "



When 300 is the vertical depth of channel secⁿ.

Box secⁿ - used in column

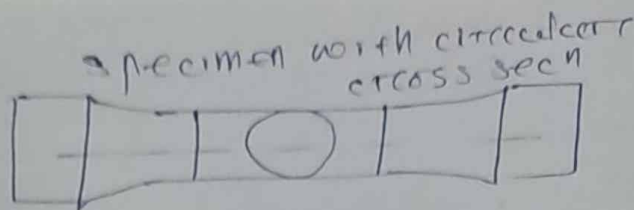


Flat secⁿ : —

ISF - IS Flat secⁿ

— used in dgm. of lacing & batten.

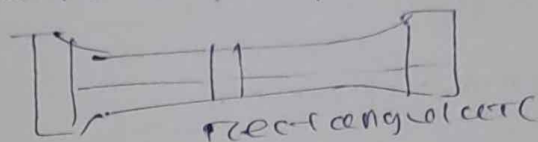
Eg. SUTSF δ
 $\downarrow$ width of plate
 $\downarrow$ thickness of plate.



Uniaxial tension test:

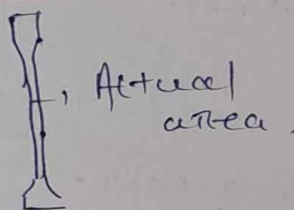
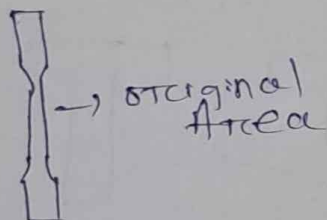
this test is of static type i.e. the load is increased comparatively slowly from zero or a certain value.

UTM $\rightarrow$ OTC tensile testing machine is used.



- The ends of the specimen are secured in the grip of the testing machine.
- There is a unit for applying a load to the specimen with a hydraulic or mechanical drive.
- There must be a some recording service by which you should be able to measure the final d.p. in the form of load or stress.

True stress & Nominal stress:



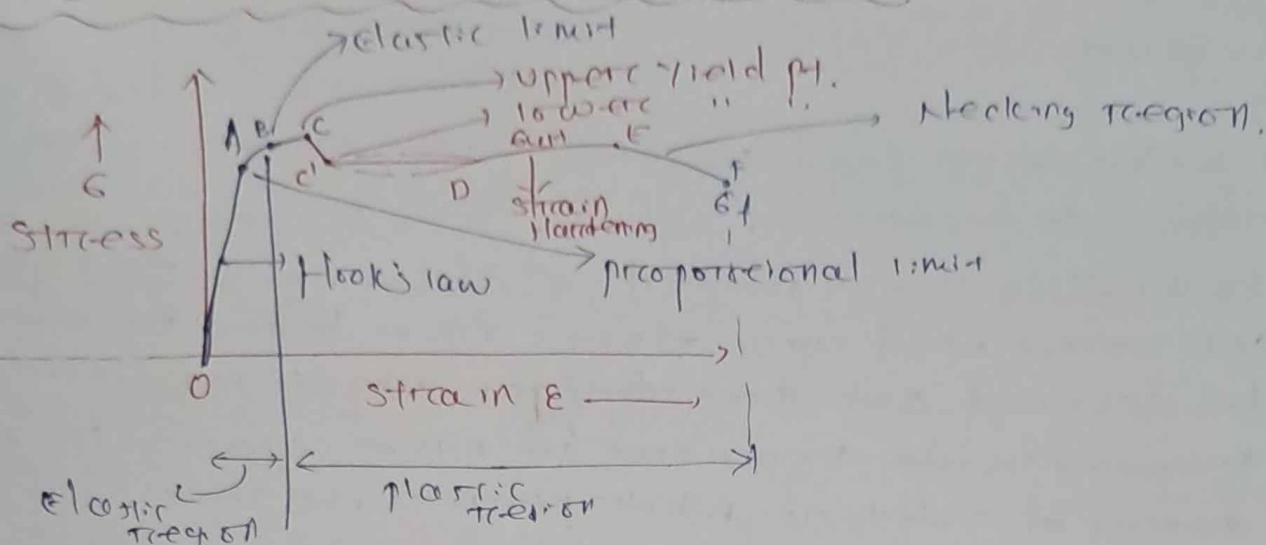
1. Nominal stress-strain or conventional stress-strain diagrams:

- Stresses are usually computed on the basis of the original area of the specimen; such stresses are often referred to as conventional or nominal stresses.

2. True stress-strain diagram:

- Since when a material is subjected to a uniaxial load, some contraction or expansion always takes place.
- Thus, dividing the applied force by the corresponding actual area of the specimen at the same instant gives the so called true stress.

STRESS-STRAIN CURVE FOR MILD STEEL



OA $\rightarrow$ proportional limit

OB $\rightarrow$ elastic " BUT OB (not linear)

- the slippage of the carbon atom with in a molecular mass leads to drop down of stress marginally from C to C'.

- C $\rightarrow$ upper yield pt.

C' $\rightarrow$ lower " " (yield stress f_y)

For ex Fe-250 $\Rightarrow f_y = 250 \text{ N/mm}^2$

$\rightarrow$ C'D $\rightarrow$ const. stress region called yield plateau.

- DE $\rightarrow$ Strain Hardening region $\rightarrow$ material starts offering resistance against deformation.

- EF $\rightarrow$ Necking region $\rightarrow$ drop down of stress occurs up to failure pt.

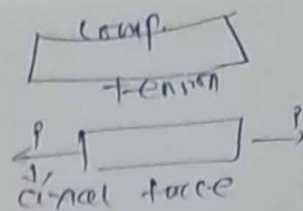
- Necking region exists only in ductile material.

- In mild steel - ABC are closer to each other, therefore it is known as linear elastic metal & yield stress & elastic stress is taken as 250 N/mm^2 .

- the fracture or failure in mild steel depends upon % of carbon present in a steel.

Permissible stress in steel structures

$$\left[\text{Permissible stress} = \frac{\text{Yield stress } f_y}{\text{FOS}} \right]$$



- It is the maxm load carried by the member without deformation.
- In working stress method, it is assumed that members can carry load upto elastic limit. hence members will be designed such that they can resist less loads as compared to the resistance of maxm capacity by proper factor of safety to whole permissible stress.
- FOS → 1.67 → for members s.t. Axial tension or comp.
→ 1.50 → " " Bending.
- Since in axial loading all fibers reach maxm stresses, but in bending only extreme fibers will reach maxm stresses. Hence FOS will be less for bending.

Working stress method :-

- In the field there are always worst combination of load (DL, LL, EL, WL, etc) hence members will be designed such that they resist more & more loads of actual use needed.
- Ultimately size & cross secn area of the member increase. Hence working / failure stress decreases.

$$\begin{aligned} \text{Working stress} &= \frac{\text{Load supplied to the members}}{\text{cross sectional area}} \\ &= \frac{\text{Yield stress } f_y}{\text{FOS}} \end{aligned}$$

Merits :-

- The members can't be failed in future having large life span.
- The dgr. is very simple.

Demerits :-

- wt. of the str. increases, hence it is uneconomical.

Plastic state or Limit state method

The dgn. of the members may reach the plastic range i.e. FOS will be designed to reach loads by considering load combinations $\times$ strength $\times$ serviceability requirements.

- Hence it is called as partial factor of safety.
- $\left[\text{Design load} = \frac{\text{corresponding characteristic load}}{\text{partial factor of safety}} \right]$

Permissible stress in steel str. :-

1. As per WSM :-

i) max^m permissible axial stress in compression is

$$\sigma_{ac} = 0.60 f_y$$

- Used in the dgn. of columns & struts.

- column is a compression member where BM exists while in case of struts, also being a compression member, BM is zero. Because strut is a component of roof trusses & roof trusses are pin jointed connection having BM = 0.

ii) max^m permissible axial stress in tension is given

$$\text{by } \sigma_{at} = 0.60 f_y$$

- It is used in tension members.

FOS $\rightarrow$ 1.67 $\rightarrow$ axial tension & compression.

- 1.50 $\rightarrow$ Bending

iii) max^m permissible stress in compression is given :-

$$\sigma_{bc} = 0.66 f_y$$

- Used in dgn. of flexural (bending) members i.e. beam, built up beam, plate girder etc.

iv) max^m permissible bending stress in tension is

$$\text{given } \rightarrow \sigma_{bt} = 0.66 f_y$$

v) max^m permissible avg. shear stress given, $\tau_{avg} = 0.40 f_y$ $\uparrow$ FOS = 2.5

vi) " " max^m " " " " $\tau_{max} = 0.45 f_y$ $\uparrow$ FOS = 2.2

v) max^m permissible bending stress is given by! —
 $\sigma = 0.75 f_y$

Increase of permissible stress! →

- When wind & earthquake load are considered, the permissible stresses in steel str. are increased by $\frac{93.33\%}{1.0}$
- " " , connections (cover & weld) are $\uparrow$ by $\frac{125\%}{1.0}$

Permissible deflection in steel str.! →

→ max^m permissible horizontal & vertical deflection given then

$$\delta = \frac{\text{span}}{325} \text{ as per WSM}$$

i) $\delta = \frac{\text{span}}{300} \rightarrow$ supported element are not susceptible to cracking

ii) $\delta = \frac{\text{span}}{360} \rightarrow$ susceptible to cracking.

Permissible stress in Gantry girders! →

- ~~For crane~~ Gantry girders are laterally unsupported beams to carry heavy loads from place to place at the construction sites.

i) For manually operated crane, $\delta = \frac{\text{span}}{500}$

ii) For electrical " " , $\delta = \frac{\text{span}}{250} \rightarrow$ upto 50 T or 500 kN capacity.

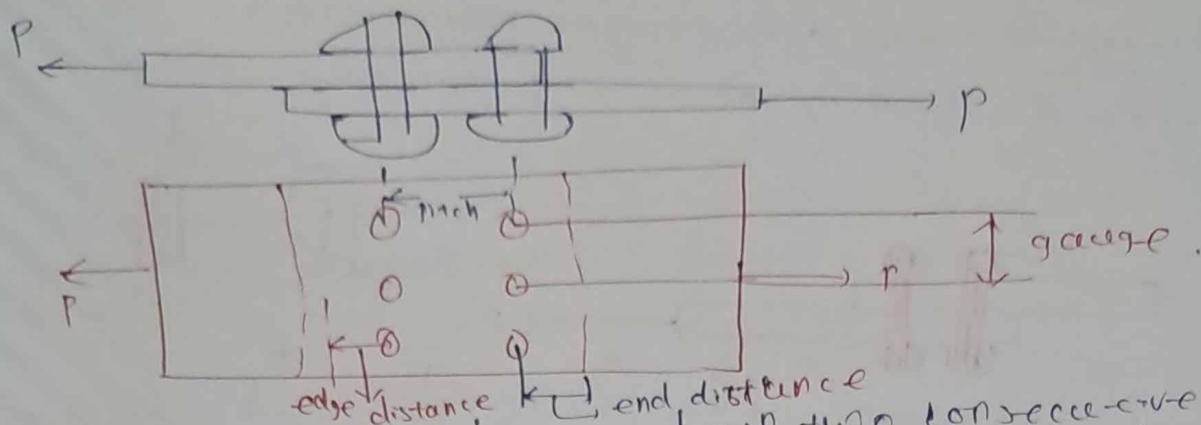
iii) " " " , $\delta = \frac{\text{span}}{1000} \rightarrow$ more than 50 T or 500 kN

FOS for diff. stresses! →

$$FOS = \frac{f_y}{f} = \frac{\text{Yield Stress}}{\text{Working Stress}}$$

Both tension & comp. $\rightarrow$ $= 1.67 = \frac{f_y}{0.60 f} \rightarrow$ axial stress

$= 1.50 = \frac{f_y}{0.66 f} \rightarrow$ bending "



1. Pitch (p) → It is the distance betⁿ two consecutive/continuous rivets measured parallel to the dirⁿ of force.
2. End distance (e) → It is the distance betⁿ centre of rivet & edge/end of the plate element, measured parallel to the dirⁿ of force.
3. Gauge distance (g) → It is the distance betⁿ two continuous rivets measured $\perp$ to the force of dirⁿ.
4. Edge distance → It is the distance betⁿ centre of rivet & edge/end of the plate element, measured $\perp$ to the force of dirⁿ.

Types of stresses

1. Direct stress

- a) Direct tensile stress
- b) " compressive "
- c) " shear "

2. Indirect stress

- a) Bending stress → $\frac{M}{I} = \frac{\sigma_b}{y} = \frac{E}{R}$
- b) Torsional shear stress, $\frac{\tau}{r} = \frac{T}{I_p}$

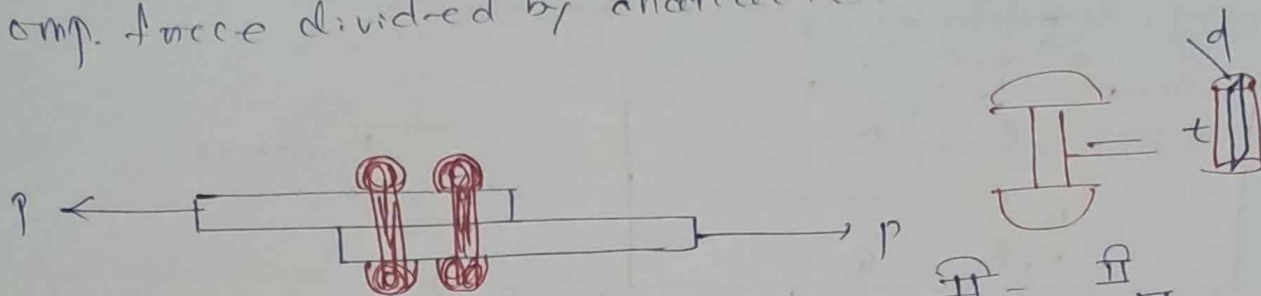
Stress! — Normal

- Direct normal stress → $\sigma_d = \pm \frac{P}{A}$
- Bending → $\sigma_b = \pm \frac{M}{I} y$
- Shear
- Primary shear stress → $\tau = \pm \frac{F \cdot y}{I \cdot b}$
- Torsional " " → $\tau = \frac{T}{J} \times r$

Bearing stresses:-

It is nothing but compressive stresses developed at the surfaces of two different materials.

- the stresses of two different materials.
- comp. force divided by characteristic area A_c to it.



shearing stresses:-

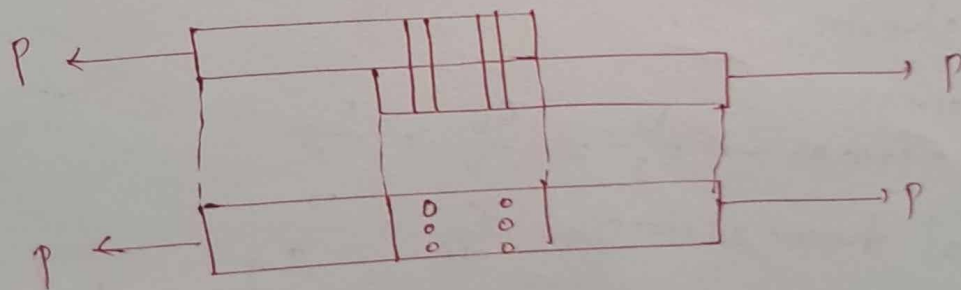
Two forces, equal & opposite in nature, when act tangential to the resisting secⁿ, as a result of which the body shears off across the secⁿ is known as shear stress.

Types of joints

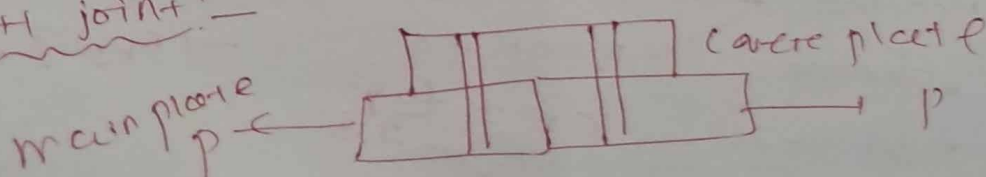
1. Lap joint:-

It is the least efficient joint as the line of action of two forces are not same.

- In lap joint, the rivets are subjected to single shear & bearing.
- these forces form couple & additional bending stresses are developed in the rivets.



2. Bolt joint:-



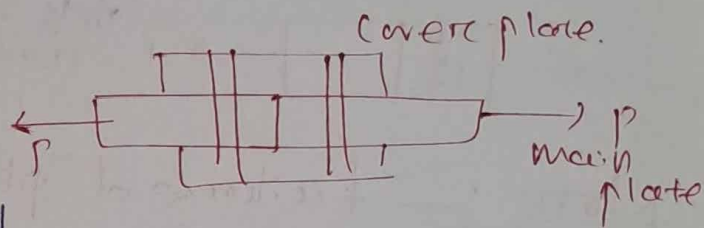
Single cover butt joint! →

The line of action of two forces is same therefore eccentricity is eliminated completely which existed in lap joint hence this joint is more efficient in carrying the force as compared to lap joint.

- But the connection is not symmetrical.
- the rivets are s.t. single shear & bearing.
- $t_{cover} \geq t_{main}$ (so that the joint doesn't fail).

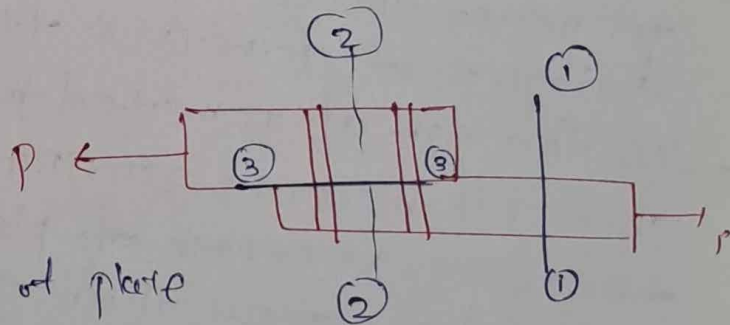
Double cover butt joint! —

- It is the most efficient joint because the line of action of two force is same & connection is symmetrical w.r.t applied load.
- the rivets are subject to double shear & bearing.
- sum of thickness of cover plate $\geq t_{main}$.

Connections! →

In steel str., various types of elements are connected together using various types of connections.

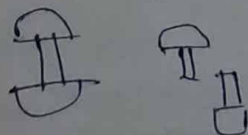
- Riveted connections
- Bolted
- Welded

Strength of plate! →

- secⁿ 1-1 → Tearing strength of plate
 secⁿ 2-2 → Bearing " " "
 secⁿ 3-3 → Shear " " "

Failure of Riveted jointFailure of rivetsShearing

Rivet gets cut into two or more pieces.

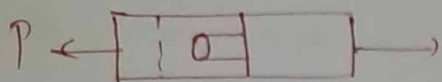
Bearing

- rivet cross secⁿ changes from circular to elliptical.



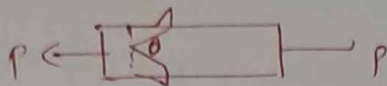
Failure of plates

i) shearing



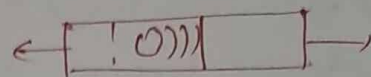
- stresses are developed parallel to the applied forces direction.

ii) splitting



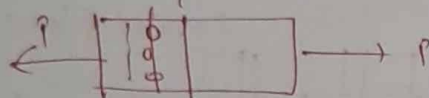
- It occurs due to diagonal tension in the plate at the rivet level.

iii) Bearing



- This plate is pushed forward by the rivet. This type of failure occurs generally due to insufficient end distance.

iv) tearing / tension failure of the plate



It is developed in the direction of applied force.

Note :- Failure of plate

- shear, bearing & splitting failure of plate are due to insufficient end distance.
- by providing the proper end distance, these three failure can be prevented.
- In the dgn. of riveted joint which should consider the remaining three failure only, i.e. shear & bearing failure of rivets & tearing failure of plate.
- In the dgn. of riveted joint, we have to ensure that shear & bearing strength of rivets is more than the tearing strength of plate because rivet failure is more dangerous than the plate failure.

Plate :-

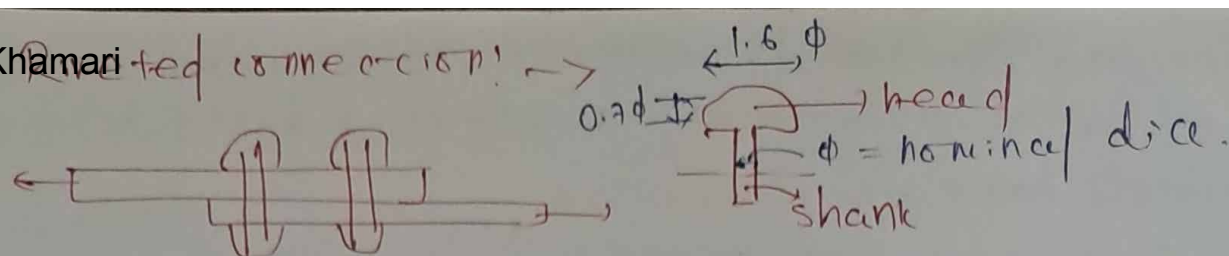
shearing
bearing
splitting

} insufficient end distance

Riveted

tearing
shearing
bearing

} -



- Rivets are inserted in the hole made to join the two members together & hammering is done to make head on other side.
- Rivets are made of mild steel. The riveting can be hot riveting (or) cold riveting.
- cold riveting is not adopted for $\text{dia} > 10 \text{ mm}$.
- In " " there is no gripping action but strength is better due to cold working.
- When hot rivet is used, it becomes plastic, it expands & fill the rivet hole completely in the process of forming a head at the other end. On cooling, the rivet shrinks in the length & dia. due to shortening of " shank length.
- The connected part becomes lighter consequently resulting in tension of unpredictable amount in a shank length & some compression in plates that are connected.
- Due to reduction of dia. of shank on cooling, this small amount of space available on cooling is provided for temp. variation of unpredictable amount.
- In hot riveting, rivets are heated to $550 - 1000^\circ \text{C}$ & hammering is done on other side to make head.
- According to the type of hammering we have:
 - i) power driven rivets
 - ii) Hand " "
- power driven rivets have better quality control & hence have a higher permissible stress.

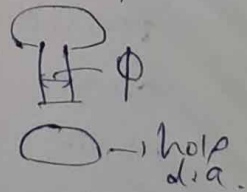
Er. Anjana Khamari can be done in the factory (or) in the field & according to these shop riveting & field riveting thus we have: —

- i) power shop rivets PDS
- ii) " driven field " PDF
- iii) Hand " " HDF

if power

Note For shop rivet
For field rivet

N/mm ²	Axial tension	shearing	bearing
PDS	100	100	300
PDF	90	90	270
HDF	80	80	250

- the nominal dia of rivet is said to be shank dia under cold condn & gross dia. of rivet is taken as dia of hole.
 - the strength of a rivet is based on its gross dia. center to center.
 - the assumption that rivet fills the hole completely.
 - For ease in connection dia. of hole is taken larger than nominal dia. of rivet thus as per IS code: —
- 

— hole dia.
- For $\phi \leq 25 \text{ mm}$
 - gross dia = $\phi + 1.5 \text{ mm}$
 - dia. hole = $\phi + 1.5$
 - For $\phi > 25 \text{ mm}$
 - gross dia. = $\phi + 2 \text{ mm}$ = dia of hole
- Due to many demerits, riveted connection is not in practice in modern steel connection.

$$\begin{aligned} \text{a) } \phi &= 16 \text{ mm} \leq 25 \text{ mm} \\ \text{hole dia} &= 16 + 1.5 \\ &= 17.5 \text{ mm} \end{aligned}$$

Welded connection is same as that of bolted connection but with the following differences:—

- the dia. of rivet to be used in the calculation is dia. of hole, whereas as for bolted connection it is the nominal dia.
- the dgn. stresses are different (IS: 800: 1984) the permissible stress are reduced for bolts.

Strength of riveted joint:—

It is taken as min of shear strength, bearing & tearing strength.

For Lap joint:—

i) For entire plate:—

a) shear strength of rivets

$$P_s = n \times \frac{\pi}{4} \times d^2 \times F_s$$

where,

n → total no. of rivets at joint

F_s → permissible shear stress in rivets

$F_s = 100 \text{ MPa (WSM)}$

F_u = Ultimate shear stress in rivet

$$\text{so in LSM} = \frac{F_u}{\sqrt{3} \times 1.25}$$

d = gross dia. of rivet (hole dia.)

$$\text{gross dia} = \phi + 1.5 \text{ mm}, \quad \phi \leq 25 \text{ mm}$$

$$= \phi + 2 \text{ mm}, \quad \phi > 25 \text{ mm}$$

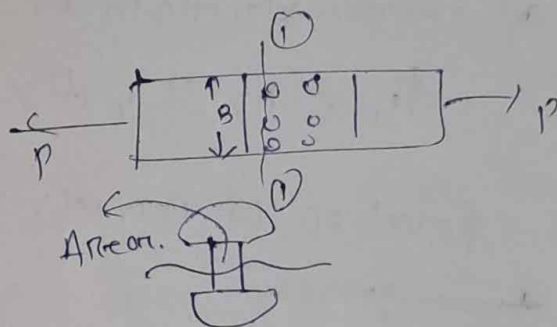
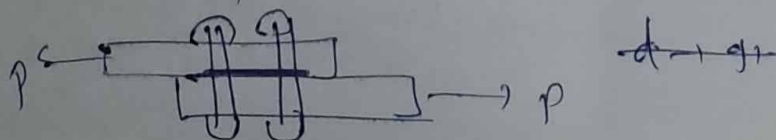
b) bearing strength of all rivets

$$P_B = n \times (t \times d) \times F_b$$

where,

t = thickness of thinner main plate.

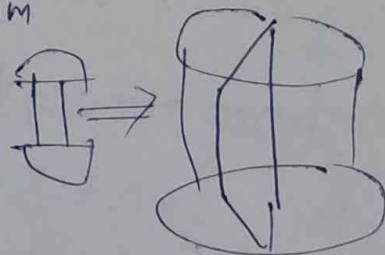
F_b = permissible bearing stress in rivets
(300 MPa in WSM)



$$S = \frac{F}{A}$$

$$\Rightarrow F = S \times A$$

$$F_s$$



Er. Anjana Khamari

$$P_t = (B - n, d) \times t \times F_t$$

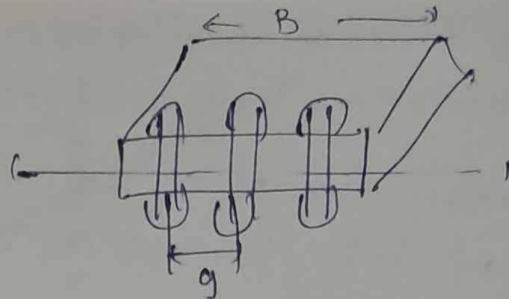
where,

n → total no. of rivets at section

B → width of the plate

F_t → permissible tensile stress in rivets

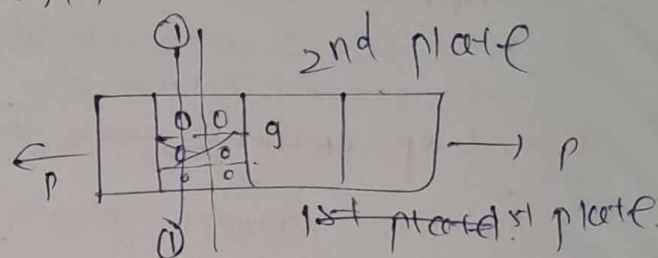
$$(F_{t1} = 0.6 f_y = 0.6 \times 250) = 150 \text{ MPa})$$



ii) For Gauge length / pitch length

a) shear strength of rivets

$$P_{s1} = n \times \frac{\pi}{4} \times d^2 \times F_s$$



n → total no. of rivets at joint in crossed gauge length

~~F_s → perm~~

b) Bearing:—

$$P_{B1} = n_1 \times (t \times d) \times F_b$$

c) tearing:—

$$P_{t1} = (g - d) \times t \times F_t$$

when pitch distance is given then $P_t = (p - d) \times t \times F_t$

g → gauge length.

Double cover butt joint:—

i) For entire width of plate

a) shear strength of rivets

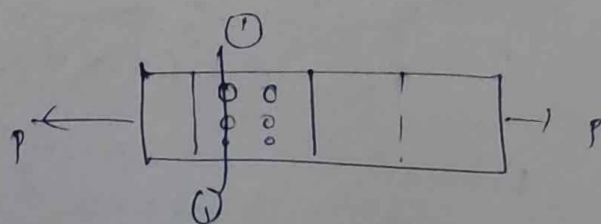
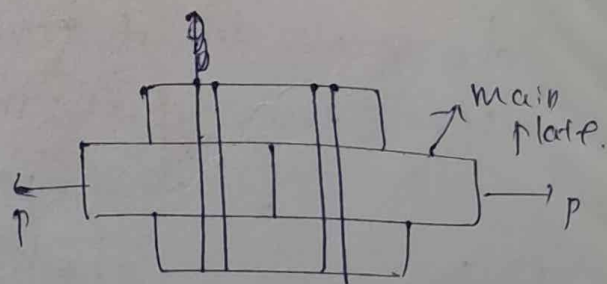
$$P_{s1} = 2 \times n_1 \times \frac{\pi}{4} \times d^2 \times F_s$$

↳ double shear

b) Bearing strength of rivet

$$P_B = n \times (t \times d) \times F_b$$

↳ min of (thickness of thinnest main plate, sum of cover plate thickness)



Bearing strength

$$P_t = (B - n \cdot d) \cdot t \times f_t$$

n → total no. of rivets at external section 1-1

t → min of (thickness of thinner main plate, sum of cover plate thickness)

ii) For Gauge length

a) shear:-

$$P_{s1} = 2 \times n \times \frac{\pi}{4} \times d^2 \times f_s$$

b) Bearing:-

$$P_{B1} = n_1 \times (t \times d) \times f_b$$

n_1 → total no. of rivets at joint in crossed gauge length.

c) Tearing:-

$$P_{t1} = (g - n \cdot d) \cdot t \times f_t$$

t → thickness of thinner main plate

n → total no. of rivets at in external section 1-1 in crossed gauge length (here 1)

* No. of rivets required at a joint, = $\frac{\text{total force at a joint}}{\text{Rivet value}}$

$$\Rightarrow n = \frac{F}{R_v}$$

* efficiency of joint, $\eta = \frac{\text{least value of } P_s, P_b, P_t}{\text{Strength of solid plate}} \times 100$

P_s = shearing strength of joint

P_b = bearing " " "

P_t = tearing " " plate

* efficiency of entire plate:-

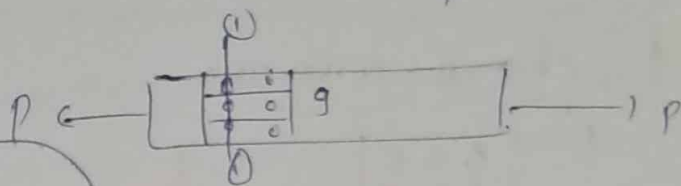
we have to ensure that P_t is less because rivet failure is more dangerous.

For entire plate:-

$$\eta = \frac{\text{least value of } P_s, P_b, P_t}{\text{Strength of solid main plate}} \times 100$$

$$= \frac{(B - n \cdot d) \times t \times f_t}{B \times t \times f_t} \times 100 = \frac{(B - n \cdot d)}{B} \times 100$$

Here n = total no. of rivets at joint

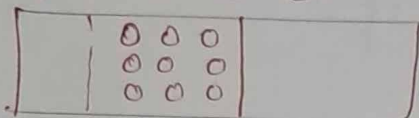


For Gauge length: —

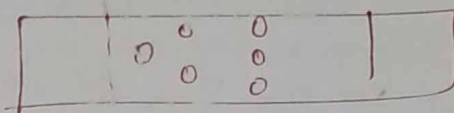
$$\eta = \frac{(g-d) \times t \times f_t}{g \times t \times f_t} \times 100 = \frac{g-d}{g} \times 100$$

Arrangement of rivets

1. Chain riveting



2. Diamond



- In chain riveting the rivets are arranged as shown: —

- 1-1, 2-2 & 3-3 shows sections at either side of the joint.

1-1 → central section main plate → outer most secⁿ

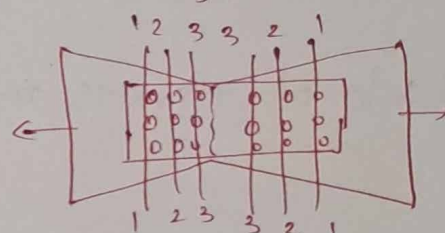
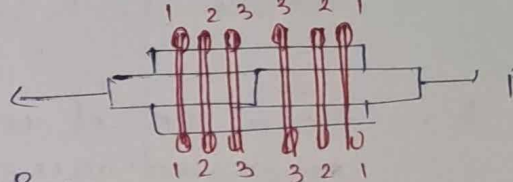
3-3 → " " of cover " → Inner " "

Strength of main plate: —

$$P_{1-1} = (B - 3d) \times t \times f_t$$

$$P_{2-2} = (B - 3d) \times t \times f_t + 3R_v$$

$$P_{3-3} = (B - 3d) \times t \times f_t + 6R_v$$



Strength of cover plate: —

$$P_{3-3} = (B - 3d) \times t \times f_t$$

$$P_{2-2} = (B - 2d) \times t \times f_t + 3R_v$$

In diamond pattern: —

secⁿ 1-1, 2-2 & so on has to be checked

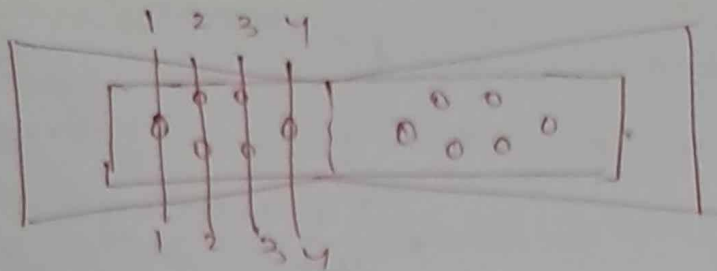
For main plate in carrying a required load, but for cover plate the last secⁿ is checked for carrying a required load.

Strength for main plate: —

$$P_{1-1} = (B - d) \times t \times f_t$$

$$P_{2-2} = (B - 2d) \times t \times f_t + R_v$$

$$P_{3-3} = (B - 3d) \times t \times f_t + 3R_v$$



- In triangular square pattern of riveting, section 2-2 is checked for main plate in carrying a required load.
- For cover plate, 4-4. main plate as it seen for cover plate is supposed to be checked for cover plate, also section 3-3 & 2-2 is also checked for safety.

Strength for main plate! —

$$P_{1-1} = (B - d) \times t \times F_t$$

$$P_{2-2} = (B - 2d) \times t \times F_t + R_v$$

$$P_{3-3} = (B - 2d) \times t \times F_t + 3R_v$$

$$P_{4-4} = (B - d) \times t \times F_t + 5R_v$$

(provision is valid for
machine
element)

Specifications as per IS 800-1984! —

min. end & edge distance = 1.5 × gross dia. of rivet

- this recommendation is provided to prevent 3 types of failure in plates! —

- splitting failure of plate
- shearing " " "
- Bearing " " "

→ For hand driven elements! —

min. (edge distance & end distance) = 1.7 × gross dia. of rivet

→ But for analysis & dgm. purpose
= 2 × gross dia. of rivet.

Pitch

- min pitch of rivet = $2.5 \times \phi$ ϕ → nominal dia of rivet
- Max pitch " " " " or weld : — t → thickness of thinner plate

In compression
 $12t$ or 200 mm
 $= 18t$ or 300 mm
 (min of two)

In tension
 $16t$
 $= 24t$ or 300 mm
 (min of two)

- the max pitch provision is provided to ensure the prevention of buckling betn the connection.

- the max pitch provision is provided to ensure the prevention of separation of plates betn connections.

Note

If the rivets are staggered (not in the same line) & if the gauge distance is smaller than 75 mm , then above recommended values in comp. & tension zone for max pitch are increased by 50% i.e.,

For comp.
 max pitch = $18t$ or 300 mm
 (min)

For tension
 $= 24t$ or 300 mm
 (min)

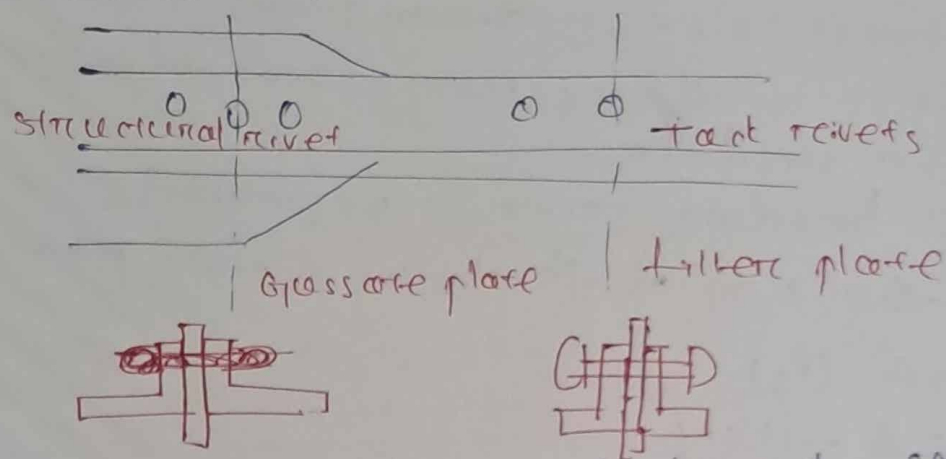
* Gauge length (g) → $\nless 100 + 4t$ or 200 mm
 max edge distance should not exceed $12t$ &

where, $\epsilon = \sqrt{\frac{250}{fy}}$

- when the members are exposed to corresponding max edge distance should not be greater than $40 + 4t$.

Tack rivets

- they are the rivets used to make the structural component as a single unit.
- they don't carry any load because we consider tack rivets not as a structural unit i.e. provided as the location of gusset plate.



- The max^m pitch provided in the case of tack rivet when two angle sections are placed back to back to gusset plate as:
 - 1000 mm in case of tension
 - less than 600 mm - comp.

Both valid for angle & channel section

- * When two plates are attached to a gusset plate back to back, then the max^m pitch is taken as:
 - $32t$ or 300 mm (min)

Unwin's formula

$$\phi = 6.04 \sqrt{t}$$

→ thickness of thinner plate

- It is used when dia of rivet is not known.

Note

- For field rivet, the permissible stress is reduced by 10%.
- the permissible stress in rivet under wind load condⁿ as per IS 800 can be ↑ by 25%.
- " " under wind & earthquake load condⁿ → ↑ by 25%.

- When thickness of cover plate is not given, then the thickness of cover plate should not be $< \frac{5}{8} t_{\text{main}}$ (thinner).
- Assumptions in dgn. of riveted joint
 - the applied axial load is assumed to be shared by all the rivets equally.
 - the tensile stress $(0.6 f_t)$, shear stress $(0.4 f_t)$ & bearing stress at their respective centres are assumed to be uniform.
 - the effect of bending stress is neglected.
 - Grip length is the sum of thickness of two plates.
 - i) Grip length (l_g)
 $l_g \geq 5 \phi \rightarrow \text{LSM}$
 - ii) $l_g \geq 8 \phi \rightarrow \text{WSM}$
 - the friction force betⁿ the plates is neglected.
 - $(g-d) \cdot f_t \leq n R_v$ (most imp. consideration).
- ① steel is mainly an alloy of $\rightarrow$ Iron & Carbon
- ② Disadvantage of steel $\rightarrow$ Little & corrosion resistance
- ③ elastic modulus of steel $\rightarrow$ $2 \times 10^5 \text{ N/mm}^2$
- ④ unit mass of steel $\rightarrow$ 7850 kg/m^3
- ⑤ poisson's ratio of steel $\rightarrow$ 0.3
- ⑥ structural steel normally has carbon content less than $\rightarrow$ 0.6 %.
- ⑦ when manganese is added to steel $\rightarrow$ improves strength & hardness of steel
- ⑧ property of high carbon steel $\rightarrow$ reduced ductility
- ⑨ min^m % of chromium & nickel added to stainless steel $\rightarrow$ 0.5%, 10.5%, 0.5%.

- (10) the effect of increase content of sulphur & phosphorus in steel $\rightarrow$ affects weldability.
- (11) (strict criteria to be considered while designing) —
structure should be adequately safe, should have adequate serviceability.
- (12) serviceability: — It means that the str. should perform satisfactorily under different loads without discomfort to users.
- (13) Analysis $\rightarrow$ determination of axial forces, BM, S.F etc.
- (14) Mostly adopted design for steel str. as per IS code $\rightarrow$ limit state Method
- (15) general construction of steel $\rightarrow$ IS 800
- (16) permissible stress = $\frac{\text{yield stress}}{\text{FOS}}$
- (17) In WSM,
working stress $\leq$ permissible stress
- (18) $\boxed{\text{Load factor} = \frac{\text{ultimate load}}{\text{working load}}}$
- (19) the eff. length of a compression member of length 'L' held in position & restrained in dirn at one end & effectively restrained in dirn but not held in position at the other end is $\rightarrow$ $\frac{L}{2}$
- (20) ~~total stress~~
~~the ratio~~ $\frac{\text{shearing stress}}{\text{shearing strain}} = \text{shear modulus of elasticity}$
In elastic limit,
- (21) A beam is defined as a structural member s.t $\rightarrow$ transverse loading
- (22) A rivetted joint can fail in $\rightarrow$ $\left\{ \begin{array}{l} \text{tearing of plate only} \\ \text{shearing of rivet} \\ \text{bearing of " " " } \end{array} \right.$

(23) Gross dia = 14 mm $\leq$ 25 mm.

$$d = \phi + 1.5 = 14 + 1.5 = 15.5$$

the gross dia. of a 14 mm nominal dia rivet is 15.5 mm.

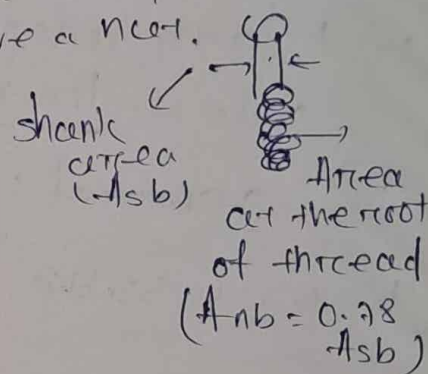
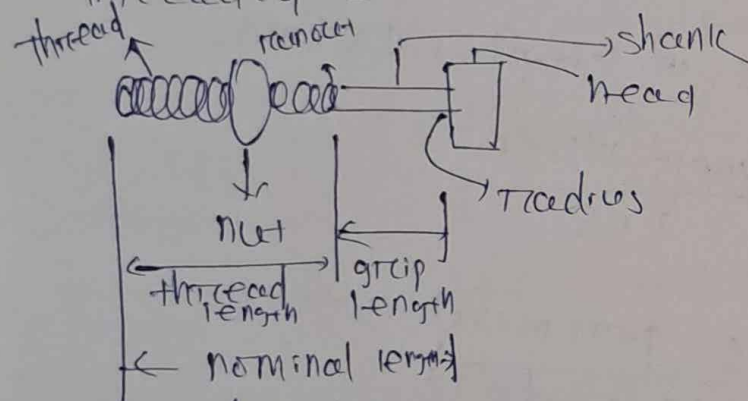
(24) the strength of field rivets as compared to shop rivets is $\rightarrow 90\%$.

(25) the max c-to-c distance betⁿ rivets in a tension member of thickness 10 mm is $\rightarrow$ 160 mm

(26) min pitch of rivets shall not be less than (where d is gross dia of rivet) $\rightarrow 2.5d$

2. Bolted connections

- A bolt is a metal pin with a head at one end & a shank threaded at the other end to receive a nut.



Types of Bolts

① Black bolt / ordinary bolt / unfinished bolts:-

It is the least expensive bolts, used for light static loads & for secondary members such as purlins, bracing etc.

- they are not recommended for connections s.t. impact load, vibration & fatigue.

- the bolts are available from 5mm to 36mm in dia. & are designated as M5 to M36.

- Bolt of property class 4.6 means:-

i) ultimate strength of bolt (f_{ub}) = 400 MPa

ii) yield " " (f_{yb}) = $0.6 \times 400 = 240$ MPa

② Turned bolts / close tolerance bolts:-

It has small tolerances & are used in no slip connection. They are mainly used machines & under dynamic loading condⁿs.

Types of bolted joints :-1. Lap joint.

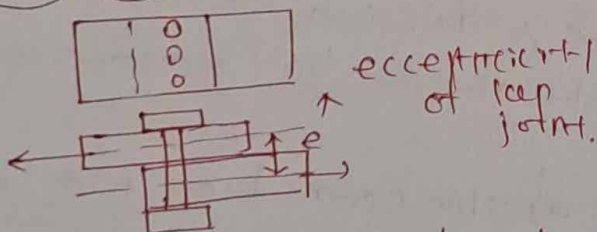
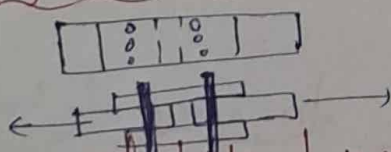
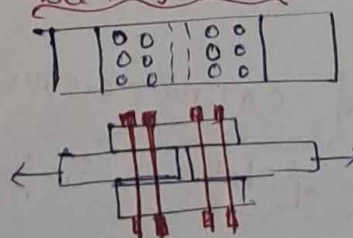
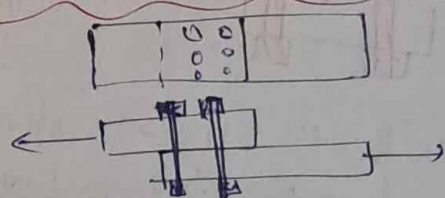
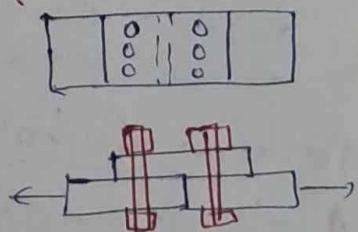
1. single bolted lap joint
2. Double " " "

2. Butt joint.

1. Double cover single bolted butt joint
2. " " double " " "
3. single " single " "

3. High strength bolt

- they are available from 16 mm to 36 mm in diameter.
- the most commonly used bolts are of 8.8 S (or) 10.9 S property class. 8 stands for high strength.
- this bolts may be tightened until they have many high tensile stresses so that the connected parts are tightly clamped together betn the bolt head & nut & friction developed betn the plate surfaces s.t. clamping force.
- the high strength bolts with specified initial tension are known as high strength friction Grip (HSFG) Bolt.

single bolted lap jointdouble cover single bolted butt jointdouble cover double bolted butt jointdouble bolted lap jointsingle cover single bolted butt jointTypes of bolted joints

- double cover butt joint eliminates the eccentricity, hence bending is eliminated.
- the load in the lap joint has eccentricity, hence a couple is formed which causes undesirable bending in the connection & bolts may fail in tension.
- to minimize the effect of bending in lap joints at least bolts in a line must be provided.

Failure Mechanism

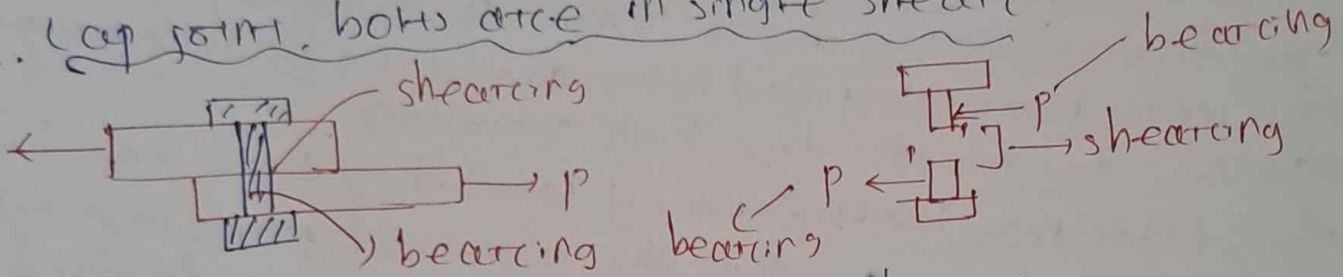
→ Load transfer from one connected part to another depends on the type of connection.

- In bearing type connection using ordinary bolts, the load transfer is by shearing & bearing.

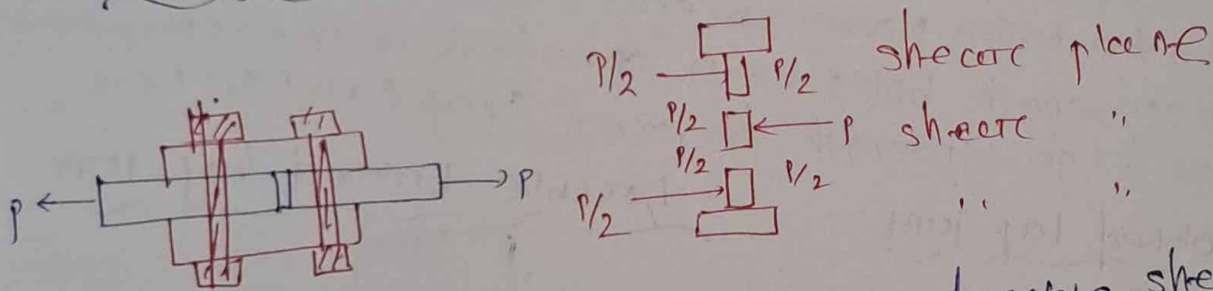
- In slip critical / slip resistance connection using HSF bolts, the load transfer is by friction.

→ Transfer of forces in lap joint & butt joint

1. Lap joint, bolts are in single shear



2. Butt joint, bolts are in double shear

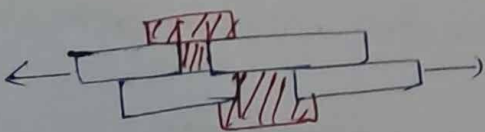


→ Bolts with single shear plane & double shear plane are called single shear bolt & double shear bolt respectively.

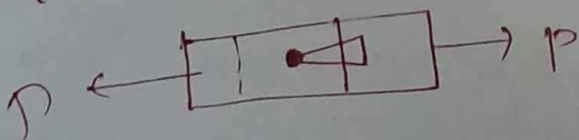
→ Shear capacity of a bolt in a double cover butt joint is double than of a bolt in a lap joint because of two shear planes.

Failure of bolted connections

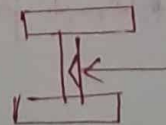
1. Shear failure of bolts



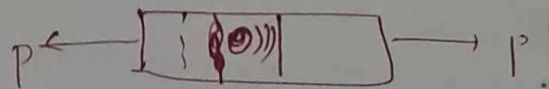
2. Shear failure of plate

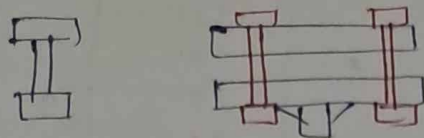
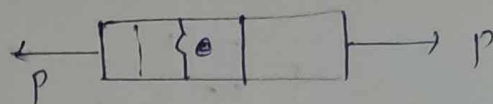
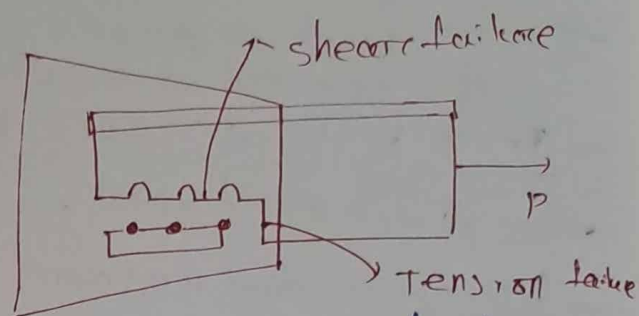
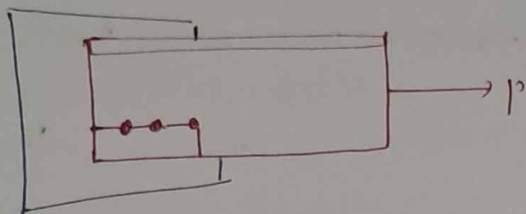


3. Bearing failure of bolts



4. Bearing failure of plate



5. Tension failure of bolts6. Tension failure of plate7. Block shear failure

- It is a limit state that combines tensile failure on one plane & shear failure on another plane.
- Block shear failure may occur when material bearing strength & bolt shear strength is high.

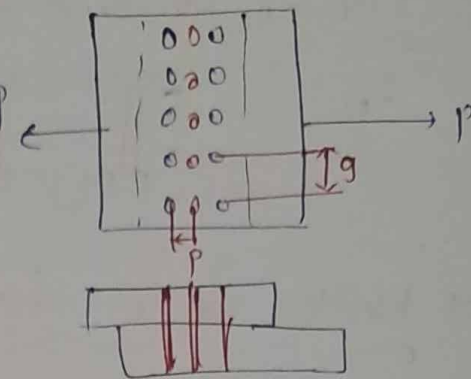
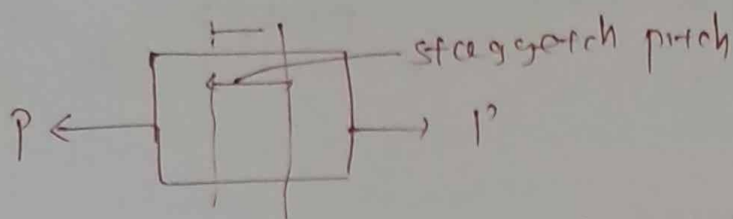
Specifications of bolted connections1. Dia. of bolt holes:

- Under normal situation, dia of bolt hole is made larger than the shank area to facilitate erection.

Nominal dia of bolt	In mm					
	12 mm	14 mm	16 mm	20 mm	24	30 36
Dia of hole	13	15	18	22	26	33 39
	+1 mm		+2 mm			+3 mm

Q In calculating the area to be deducted for bolts of 36 mm dia. the dia. of hole shall be taken as →

36 mm → nominal dia. → $\phi > 24 \text{ mm}$
 dia. of hole = $b + 3 \text{ mm} = 36 + 3 = 39 \text{ mm}$

2. Pitch (p) & Gauge (g)

→ min^m pitch & gauge = $2.5d$

d = nominal dia. of bolt

→ Pitch is the distance betn two consecutive bolts in

the dirn of force.

→ Gauge is the distance

the dirn of force.

- Bolts are kept apart at a sufficient distance & a min^m pitch is ensured due to:

i) to prevent bearing failure of members betn the two bolts.

ii) to permit eff. installation of bolts.

max^m pitch

- It is desirable to place the bolts sufficiently close together for the following reasons:-

- To reduce the length of connection & gusset plate i.e. to have a compact joint.

- To have uniform stress in bolts.

1. For tension member → $p \nless 16t$ or 200mm

2. For comp. " → $p \nless 12t$ or 200mm

3. For rows near the edge → $p \nless 4t + 100\text{mm}$ or 200mm

4. Staggered pitch -
When the gauge doesn't exceed 25mm, the pitches in 1, 2, & 3. may be increased by 50%. When bolts are regularly staggered.

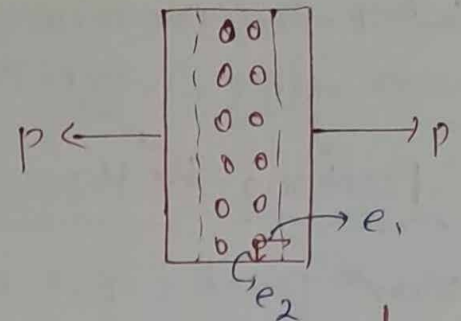
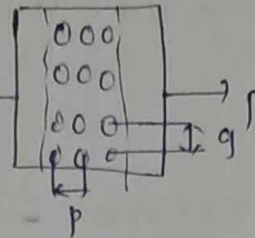
5. max^m gauge → $g \nless 32t$ or 300mm

max^m pitchNote

For wide plates, pitch is defined as centre to centre distance of bolts measured along the length of the connection.

Pitch (p) & Gauge (g)maxm pitch

- It is assumed that the load on the joint is shared equally among all the bolts, in short length joints the force in bolts will be redistributed by plastic action & hence the bolt will share load equally.
- However in long joints (> 15 times dia. of both) the shear deformation is not uniform.
- The bolt at the ends of the joints are heavily stressed resulting in a progressive failure called 'unbuttoning'. Thus a compensating joint is desirable.



e_1 → edge distance
 e_2 → end distance

(3) Edge & end distance

- Distance from the centre of bolt hole to the adjacent edge of the member at right angles to the direction of stress is called edge distance.
- Distance from the centre of bolt hole to the adjacent edge of the member in a direction of stress is called end distance.

- Bolt holes should not be placed too near the edge due to:
- the failure of plate in tension may be take place.
 - the steel of the " opposite to the hole may be bulge & crack.

→ Min^m end or edge distance = $1.7 d_o$
 (for sheared or hand frame cut edges).

→ min^m end or edge distance = $1.5 d_o$
 (for machine cut & planed edges)

d_o = dia. of bolt hole

→ max^m end or edge distance = $12 + \epsilon$

$\epsilon = 200\sqrt{250/f_y}$, t = thickness of thinner plate

When the members are exposed to corrosive environment
 max^m edge distance $\geq 40 \text{ mm} + 4t$.

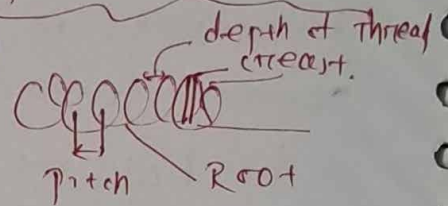
Tacking Bolts

- max^m pitch = $32t$ or 300 mm $\rightarrow$ when plates are not exposed to weather.
- = $16t$ or 200 mm $\rightarrow$ " " exposed to weather

* For two members placed back to back, the max^m pitch of tacking bolts $\geq 1000 \text{ mm}$.

(154) Assumptions in the analysis of simple Bolted joints

- Friction betⁿ the plates is neglected & load is resisted by bolts, in bearing & shearing.
- In case of bolts if threads occurs in the plane of shear, the eff. area resisting shear is taken as the area at the root of thread.
- However if " don't occur in plane of shear, eff. area is the cross-section area of the shank.
- The applied load is equally resisted by all the bolts.
- Distribution of stress on the portion of plate betⁿ the bolt holes is uniform, i.e., stress conc. around the hole is neglected.
- This assumption is made for ease in calculation. However at the time of collapse this assumption would be actually valid.
- * The bending stress in the bolt is neglected.
- * " " " is assumed to be uniform over the nominal contact area betⁿ the plate & bolts.



Strength of bolt in bearing type connection

Dgn. strength of bolt = $\min \left\{ \begin{array}{l} \text{Dgn. shear strength of bolt} \\ \text{" bearing " " " " } \end{array} \right.$

$$V_{db} = \min \left\{ \begin{array}{l} V_{dsb} \\ V_{dpb} \end{array} \right.$$

$$V_{dsb} = \frac{V_{nsb}}{\gamma_{mb}} \rightarrow \text{nominal shear strength of bolt}$$

$\gamma_{mb} \rightarrow 1.25 \rightarrow \text{partial safety factor for material}$

$$V_{dpb} = \frac{V_{npb}}{\gamma_{mb}} \rightarrow \text{nominal bearing strength of bolt}$$

For safety,

$$V_{sb} \leq V_{db} \text{ (also called bolt value)}$$

$\rightarrow$ Factor shared load in one bolt.

A) shear strength of bolt

$$V_{dsb} = \frac{f_{ub}}{\sqrt{3} \gamma_{mb}} (n_n A_{nb} + n_s A_{sb}) \quad B_1, B_2, B_{pk}$$

Where,

$V_{dsb} \rightarrow$ Dgn. shear strength of bolt

$f_{ub} \rightarrow$ Ultimate

$\gamma_{mb} \rightarrow 1.25$

$n_n \rightarrow$ no. of shear planes with threads intersecting the shear plane

$n_s \rightarrow$ " " " " without " " " " " "

$A_{nb} \rightarrow$ net tensile area of bolt (etc) area at the root of thread = $0.78 A_{sb}$

$A_{sb} \rightarrow$ nominal shant area of bolt.

$B_1, B_2, B_{pk} \rightarrow$ Reduction factors taking into the effect of long joints, large grip length & packing plates.

Er. Anjana Khamari shear case -

$$V_{dsb} = \frac{I_{ceb}}{\sqrt{3} \times 1.25} (1 \times A_{nb})$$

- Unless specified V_{dsb} would be calculated corresponding to shear plane intersecting the thread.

i) for double shear case -

$$V_{dsb} = \frac{I_{ccb}}{\sqrt{3} \gamma_{mb}} (1 \times A_{mb} + 1 \times A_{sb})$$

- Under the assumption that one of the shear plane is intercepting the root of thread & other is intercepting the shank.

B) Bonding strength of both

$$V_{dpb} = \frac{V_{npb}}{V_{mb}}$$

$$= 2.5 \times 10^3 \times dx + x \times f_u$$

where,

d = nominal dia. of bolt

t = summation of thickness of plate elements experiencing bearing in same dir'n

2.5 is const. whose value corresponds to hole elongation about 6 mm.

$\sigma_c = 6 \text{ mm}$.
 $k_b = \min \left\{ \frac{e}{3d_0}, \frac{P}{3d_0} - 0.25, \frac{f_{cb}}{f_u} \times 1 \right\}$

e → end distance

$p \rightarrow p + ch$

d_0 - dia. of bolt hole

Sub ultimate strength of bolt

place.

→ Bearing failure in the bolts is possible only if the bolts used are of very low grade & plate joint are of high grade which is not possible.

- These are the bearing strength of bolted connection is a term of strength of connected plates & the arrangement of bolts together than grade of bolts.
- the bearing strength is also a term of bolt hole.
 - the " " is calculated where is for standard bolt holes, for oversized & short slotted holes it is 0.7 times the bearing strength & for slotted holes it is 0.5 times of the " " .

c) Tensile strength of bolt

$$T_{db} = \frac{T_{nb}}{\gamma_{mb}} = \frac{0.9 f_{ub} A_{nb}}{1.25}$$

net tensile area of bolt = $0.78 A_s b$

$$T_{db} \leq \frac{f_{yb} A_{sb}}{\gamma_{mo} \rightarrow 1.1}$$

(161) Dgn. strength of plate

- the plate may fail by: -

i) shearing of plate -

It can be avoided by keeping sufficient edge distance

ii) yielding of plate -

For gross secⁿ yielding: -

$$T_{dg} = \frac{f_y A_g}{\gamma_{mo} \rightarrow 1.1}$$

gross area of solid plate

dgn. tensile strength in gross secⁿ yielding

iii) Rupture of plate -

For net secⁿ rupture: -

$$T_{dn} = \frac{0.9 f_u A_n}{\gamma_{m1}}$$

Where,

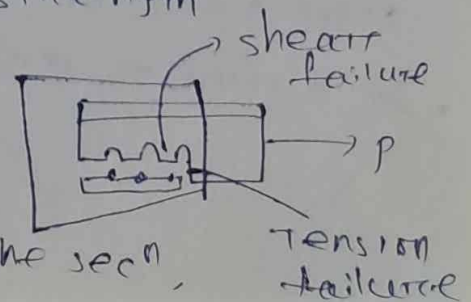
T_{dn} = dgn. tensile strength in rupture.

A_n = eff. net area of secⁿ

- factor 0.9 is introduced as there is no reserve strength beyond ultimate strength

iv) Block shear failure -

- when a block material within the bolted area breaks away from the remainder portion of the secⁿ.



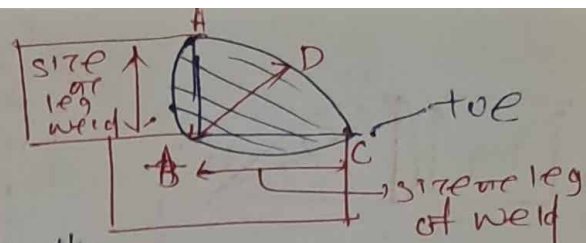
Er. Anjana Khamari

- area.
- $T_{db} = \min \left\{ \begin{array}{l} \text{shear yielding} \times \text{tension} \\ \text{"} \quad \quad \quad \text{repture} \times \text{"} \end{array} \right. \text{repture}$
- $\downarrow$
- $= \frac{0.9 f_u A_{vn}}{\sqrt{3} \gamma_{m1}} + \frac{f_y A_{tg}}{\gamma_{m0}}$
- $\frac{f_y A_{vg}}{\sqrt{3} \gamma_{m0}} + \frac{0.9 f_y A_{tn}}{\gamma_{m1}}$
- both.

- ### 3. Welded connections $\rightarrow$

 square corner
 single v
 double v
 single bevel
 double bevel
 single u
 double u
 single j
 double j
 double v - furnished
 with wash on both sides

- This type of weld is used when the members are in same plane.
- It is also termed as groove weld.
- It is used to join structural members carrying direct comp. & tension.
- It is used to make tee joint & butt joint.

2. Fillet weld :-

AB or BC $\rightarrow$ size of weld
 BD $\rightarrow$ throat thickness (t_t)

- This type of weld is used when the members to be connected overlap each other.
- A fillet weld is a weld approximately triangular cross section joining two surfaces at right angles to each other in lap joint or tee joint.
- The part of weld which is assumed to be eff. in transferring the stress is called throat.
- It is assumed that fillet weld always offers resistance in the form of shear.
- The dgn. of only is done only for shear in fillet weld.

[t_t = min dimension in fillet weld.]

- The eff. length of fillet weld should not be less than $4 \times$ thickness of weld (s)

$$L_{eff} = 4 \times \text{thickness of weld (s)}$$

- The size of normal fillets shall be taken as the min weld leg size.

- It should not be used if the angle betⁿ fusion faces is less than 60° & greater than 120° .

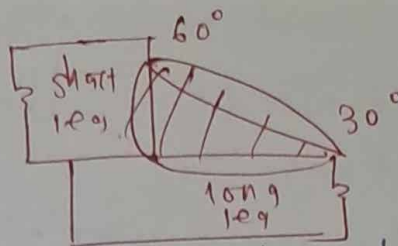
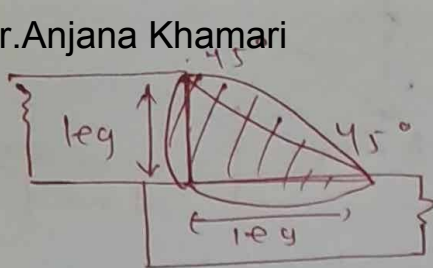
- In weld, angle should be betⁿ 60° to 120° .

$$[t_t = K \times s \text{ (size of weld)}]$$

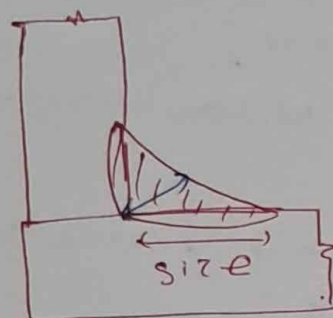
Table-22 value of K for diffⁿ angles betⁿ fusion faces
 clause (10.5.3.2)

Angle bet ⁿ fusion faces $\rightarrow$	$60^\circ - 90^\circ$	$91^\circ - 100^\circ$	$101^\circ - 106^\circ$	$107^\circ - 113^\circ$	$114^\circ - 120^\circ$
const. K $\rightarrow$	0.70	0.65	0.60	0.55	0.50

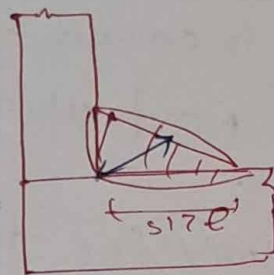
Ex! $\rightarrow t_t = (s) \sin 45^\circ$
 $= 0.7s$



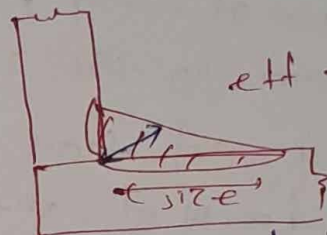
- When the cross section of filled weld is 45° , isosceles Δ , it is known as a standard fillet weld. It is generally used.
- When the cross section of filled weld is $30^\circ \times 60^\circ \Delta$, it is known as special fillet weld.



concave



convex



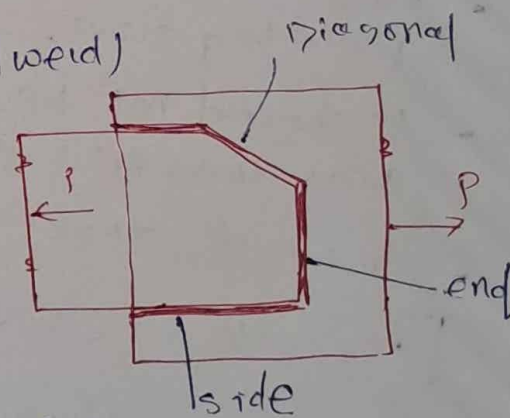
Miter fillet weld

- A fillet weld is termed as concave fillet weld or convex fillet weld or miter depending on the weld face in it.
- concave or convex are approximately flat.

- It is termed as normal fillet weld or deep penetration fillet weld depending upon the depth of penetration beyond the root is less than 2.4 mm or more respectively.

i) side filled weld (longitudinal filled weld)

It is stressed in longitudinal shear, i.e., a filled weld, the axis of which is parallel to the direction of the applied loads. It is also



ii) end filled weld (transverse)

It is a stressed in shear, i.e., a filled weld, the axis of which is at right angle to the direction of the applied load.

iii) diagonal filled weld

- It is a fillet weld the axis of which is inclined to the direction of the applied load.
- It is placed on the sides or end of the base metal & it is s.d. shear along with tens. or comp. & usually bending.

1. size of fillet

min size of the weld :-

- If the thickness of thicker part :-

up to 10 mm $\rightarrow$ 3 mm

betⁿ 11 mm to 20 mm $\rightarrow$ 5 mm

21 mm to 32 mm $\rightarrow$ 6 mm

will have to be taken.

above 32 mm $\rightarrow$ 10 mm

more than 50 mm $\rightarrow$ special precaution like preheating

- When min size of fillet weld $>$ thickness of thinner part, then min size of weld = thickness of thinner part.

- It depends on the thickness of thicker plate.

- If thickness is not given, then we assume, $s = 3 \text{ mm}$

thickness of thicker plate (mm)

min size of weld (mm)

0 - 10

3

11 - 20

5

21 - 32

6

> 32

8 (if > 50 , then 10 mm)

max size of weld

- It also depends upon size of thickness of thinner plate.

case-1

In square edge

max size = thickness of thinner plate - 1.5 mm

case-2

At rounded edge.

$= \frac{3}{4} t$ (75% of the thickness of thinner plate)

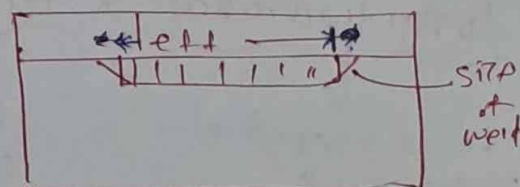
Eff. length of weld

- It depends upon the size of weld.

eff length = Actual length

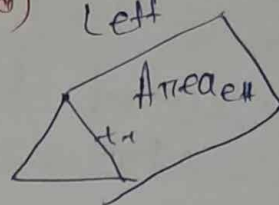
$- 2 \times \text{size of weld}$

- It should not be less than 4 times the size of weld.



Left

$$Area_{eff} = L_{eff} \times t_t$$



Load carrying capacity of weld or shear strength of weld, $P = F_s \times L_{eff} \times t_t$

$$= \text{permissible shear stress} \times \text{eff. area of weld}$$

$t_t \rightarrow$ throat thickness

$L_{eff} \rightarrow$ eff. length of weld.

$F_s \rightarrow$ permissible shear stress = 100 MPa (WSM)

$F_u \rightarrow$ ultimate tensile stress in weld metal.

$$LSM = \frac{F_u}{\sqrt{3} \times 1.25} \quad \left(\begin{array}{l} 1.25 \text{ for shop weld} \\ 1.5 \text{ for field weld} \end{array} \right)$$

max pitch, $p = 12t$ or 250 mm $\rightarrow$ comp. zone.

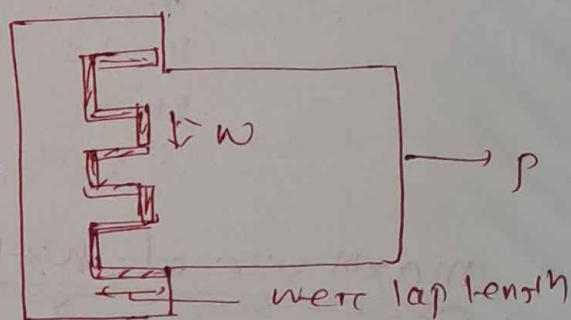
max pitch, $p = 16t$ or 200 mm $\rightarrow$ tens. "

slot welding

$w =$ width of slot

$= \max^m (25 \text{ mm} \times 3t)$

- If overlap length is limited, then the slot welding is done by making slots in the connection plate.



a thickness of plate, $t = 8 \text{ mm}$

slot width $= w = 3t = 3 \times 8 = 24 \text{ mm}$

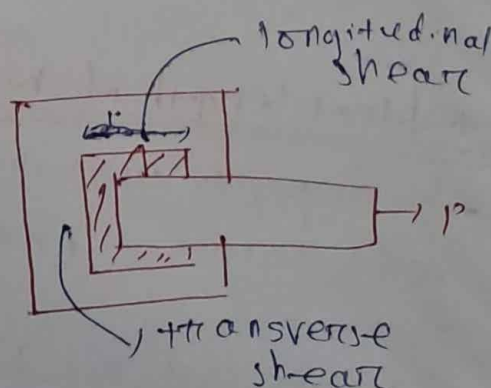
$w = \max^m (25 \text{ mm} \times 3t)$

$= \max^m (25 \text{ mm} \times 24 \text{ mm}) = 25 \text{ mm (min)}$

longitudinal & transverse shear

Load & length of weld are same dirⁿ.

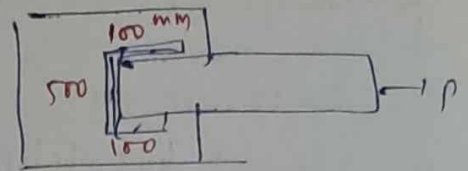
Load & length of weld are $\perp$ to each other



Note

Strength of transverse filled weld is about 30% more than longitudinal filled weld.

- A fillet welded joint of 6mm size is shown.
- the welded surface may be 60° to 90° .
- $F_s = 108 \text{ N/mm}^2$ = permissible stress



$$t_w = 0.75 = 0.7 \times 6 = 4.2 \text{ mm}$$

Safe load that can be transmitted by the joint,

$$P = F_s \times t_w \times \text{length}$$

$$= 108 \times 4.2 \times 250 = 113.4 \text{ kN.}$$

Compression member

pression.

- Structural members s.t. axial compressive force.
- their dgn. is governed by strength & buckling.
- most commonly used comp. member is column.
- other comp. members are strut, truss, frame, etc.

Column

- It is a structural member mainly s.t. comp.
- BM can also exist in this member.
- It is used for comp. of frame, i.e. RCC & steel frame.

Strut

- It is a comp. member whose BM is zero because it is used in roof truss as a comp. member.

Truss

- B.M = 0 everywhere.
- It is a str. in which all the members are either s.t. tension or comp.

Frame

- It is a str. which is s.t. BM also in addition to tension & comp.

Stanchion

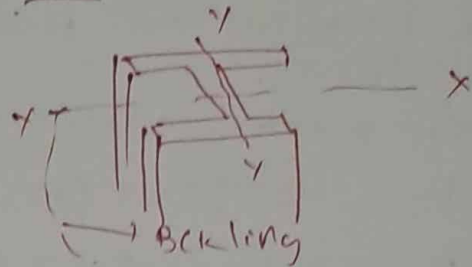
- the vertical comp. member in RCC building is called column while for a steel building it is called stanchion.

Beam

- the principal comp. member in a frame is called beam.

Methods of failure of column :-

- 1- squashing
- 2- local buckling
- 3- Flexural "
- 4- torsional "
- 5- Flexural torsional buckling

Squashing

When the length is relatively small & the component plate elements are prevented from local buckling, then the column will be able to attain its full strength, i.e., squash load.

$$[\text{Squash load} = \text{yield stress} \times \text{Area of cross-section}]$$

Local buckling

- Failure occurs by buckling of one or more individual plate elements.
- Ex! - flange or web locally prior to overall buckling of column.

Flexural buckling

- In this mode, failure of the member occurs by excessive deflection in the plane of weaker principal axis.
- In the fig, x-x & y-y axis are shown. $I_{xx} > I_{yy}$, so the resistance about y-y axis is less as compared to x-x axis. Hence buckling will occur about y-y axis.

Torsional buckling

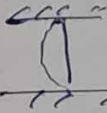
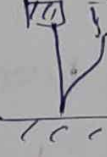
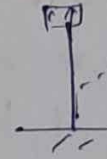
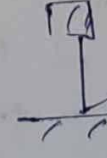
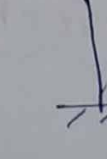
- this type of failure is caused by twisting about longitudinal axis of member.
- ~~this type~~ It can occur only in doubly symmetrical cross section with very slender cross sectional elements.

Flexural torsional buckling

- It is caused by combination of flexural & torsional buckling.
- the member bends & twists simultaneously.
- This type of failure occurs only in unsymmetrical cross sections & singly symmetrical " " "

Effective length

- In SOM, we use theoretical value & in dgn. we use IS recommended value.
- For laced columns, above values are $\uparrow$ by 5%.
- For battened " " " " " " 10%.
- eff. length is slightly ~~theoretical~~ ^{theoretical} than the theoretical value to account for the lack of 100% fixity at support.

Sl. No.	Degree of End Restraint of compression members	Fig.	theo. value of eff. length	Reco. value of eff. length
1.	Effectively held in position & restrained against rotation in both ends.		0.50l	0.65l
2.	Held in position at both ends, against rotation in one end		0.70l	0.80l
3.	position in both ends but not restrained against rotation		1.00l	1.00l
4.	Held in position & restrained in one end, & the other " against rotation but not held in position.		1.00l	1.20l
5.	Held in position & restrained in one end, & at the other partially restrained against rotation but not held in position.		—	1.50l
6.	Effectively held in position at one end but not restrained against rotation, & at the other end restrained against rotation but not held in position		2.00l	2.00l
7.	eff. held in position & restrained against rotation at one end but not held in position nor restrained against rotation at the other end.		2.00l	2.00l.

- Load capacity of a column depends upon the end condⁿs
Strongest column is both end fixed.
- the most efficient cross section is resisting compression is thin hollow circular secⁿ or '4 angle box secⁿ' because for a given cross-section area, MOI is max^m so load carrying capacity is max^m.
 - the most efficient cross section in resisting BM is I-section because for a given cross section area, section modulus & plastic modulus are max^m for I-section.
 - As per IS 800, the permissible axial compressing stress is given by Rankin's merchant formula:

$$\sigma_{ac} = \min \text{ of } \begin{cases} 0.6 f_y \\ \frac{0.6 f_y}{\left[(F_{cc})^2 + (f_y)^2 \right]^{1/2}} \end{cases}$$

$$F_{cc} = \frac{\pi^2 E}{\lambda^2}$$

λ = Imperfection factor = 1.4

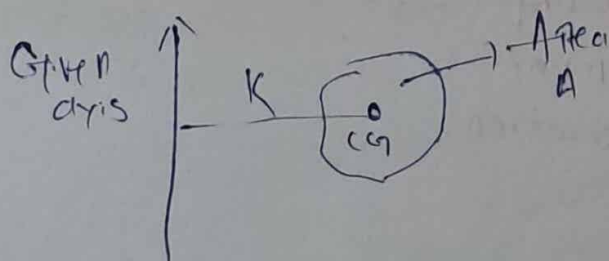
Unsupported length of column —

It is the max^m clear distance betⁿ bottom of the floor level & top of beam.

eff. length of column —

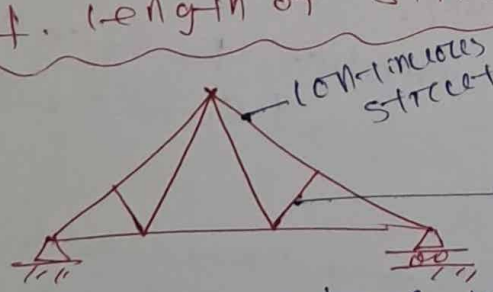
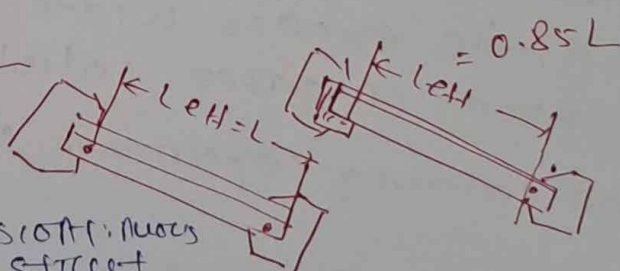
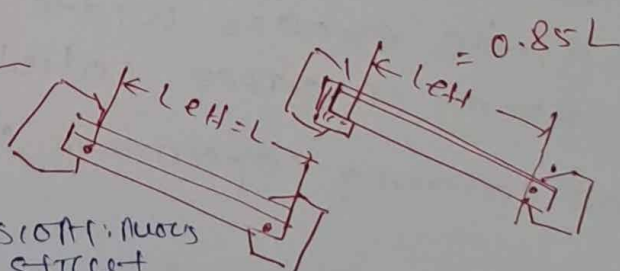
It is length of column betⁿ pts. of zero moment or distance betⁿ pts. of contra flexure.

Slenderness ratio = $\lambda = \frac{\text{eff. length}}{\text{radius of gyration}} = \frac{L_{eff}}{r_{min}}$



It is the distance such that its square multiplied by area gives moment of inertia about the given axis.

$$r_{min}^2 \times A = I \Rightarrow r_{min} = \sqrt{\frac{I}{A}}$$

Sl. no.	Max value of 'eff. slenderness ratio'	Min 'eff. slenderness ratio' (KL/r)
1. A member carrying comp. loads resulting from dead loads & imposed loads	180	
2. A tension member in which a reversal of direct stress occurs due to loads other than wind & seismic load.	180	
3. A member s.t. comp. forces resulting only from combination with wind/earthquake actions, provided the deformation of such member doesn't adversely affect the stress in any part of the str.	250	
4. comp. flange of a beam against lateral torsional buckling.	300	
5. A member normally acting as a tie in a roof truss or a bracing system not considered eff. when s.t. possible reversal of stress into comp. resulting from the action of wind or earthquake force.	350	
6. Members always under tension (other than pre-tensioned members).	400	
- Tension members, such as bracings, pre-tensioned to avoid sag, need not satisfy the max slenderness ratio limits.		
<u>Eff. length of strutt</u>		
		
		
		
- If a strut span betn two joint only. It is called as discontinuous strut.		
- If a strut span betn more than two joints then it is called continuous strut.		

If a single angle discontinuous struts is connected at each end, then $L_{eff} = L$

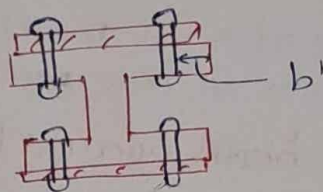
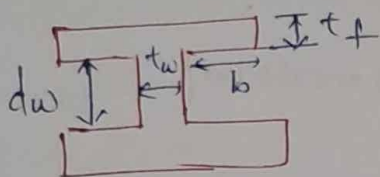
axial comp. stress $\sigma_{ac} = 0.8$

$\sigma_{ac} \rightarrow$ permissible stress is reduced by 20%.

- If a single angle discontinuous struts is connected by two or more rivets or weld, then $L_{eff} = 0.85L$.

$$[\sigma_{ac} = \sigma_{ac}]$$

Local buckling of Flange & Web plate of I-section



$b =$ width of flange from face of web.

- width of outstand is measured from center line of rivet to extreme edge for built up section.

- To prevent local buckling due to comp. as per IS 800: specify the following condⁿ:-

$$\frac{b}{t_f} \leq 16 \text{ (WSM)}$$

$$\frac{d_w}{t_w} \leq 50 \text{ (WSM)}$$

$$\frac{b}{t_f} \leq 8.4 \text{ (LSM)} \rightarrow \text{plastic section}$$

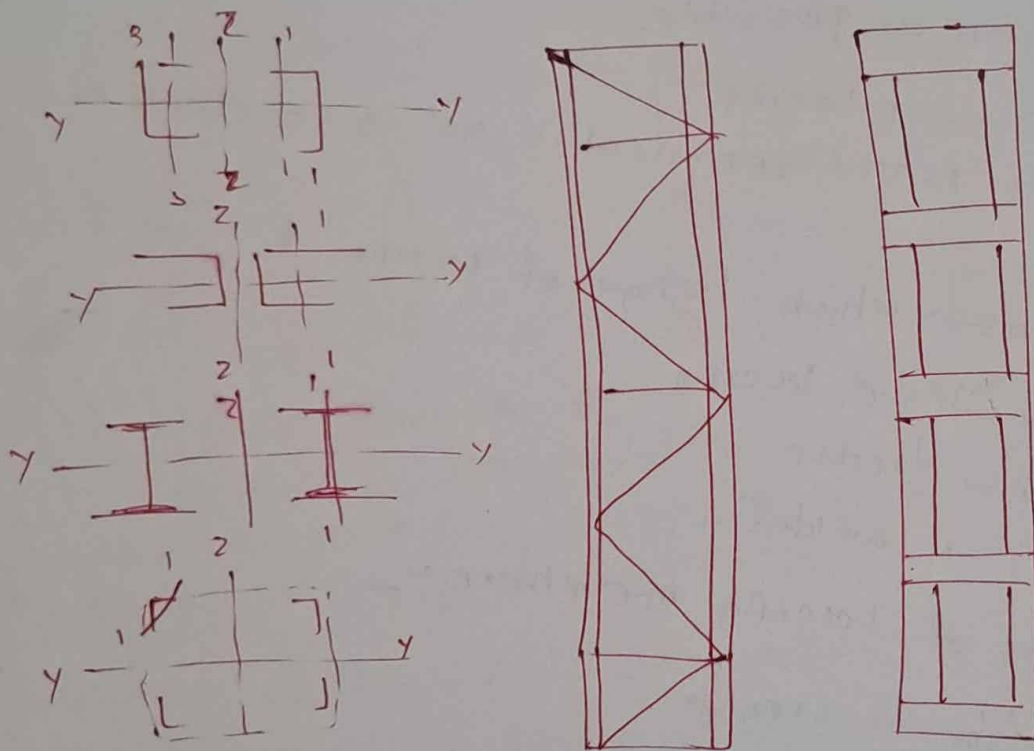
- If the flange & web plate dimensions exceed the above limits, the excess width should be neglected (not considering in area calculation).

- Load carrying capacity in comp. members, $P = \sigma_{ac} \times A_g$
($\sigma_{ac} = 0.6 f_y$)

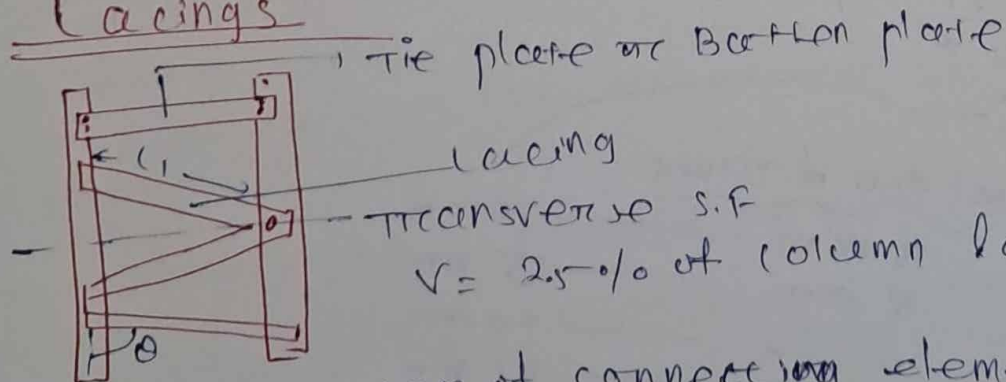
Built up column

- The size & shape of rolled section are limited because of limitations of rolling mills, so when rolled sections don't furnish the required sectional area or when a special shape or large radii of gyration is required in two different dirⁿs, built up columns are used.

- widely used in steel construction especially when the eff. lengths are greater & the comp. forces light.
- they are composed of two or more parallel main components interconnected by lacing or batten plates.
- the greater the distance betn the chord axes, the greater is the moment of inertia of the built-up cross section, the $\uparrow$ in stiffness, however is counterbalanced by the $\uparrow$ wt. & cost of the connection of members.
- It should be noted that built-up columns (especially battened built-up columns) are more flexible than solid columns w/ the same M.I.



Lacings



- Lacing is a system of connecting elements in built-up column.
- It makes the components of column act as a single unit.

- If the component of column are each very close to each other, then thick rivets are used to make them act as a single unit.
- If the spacing of component is more than the rivets are useless & so we use lacing or batten.

Inclined member - Lacing
Horizontal " - Batten

- It is idealised as truss element, i.e., the core st. either to tension or comp.
- B.M. $= 0$ $\rightarrow$ in lacing.
to ensure that B.M. is 0, provide only one rivet at each end as far as possible.
- max $l = 145$ $\rightarrow$ in lacing
- Angle of lacing w.r.t vertical is 40° to 70° (welding 60° to 90°).
- If θ decreases then length of lacing $\uparrow$.
- $l_{eff} = L_1$ $\rightarrow$ single lacing
 $= 0.7 L_1$ $\rightarrow$ double "
 $= 0.7 L_1$ $\rightarrow$ welded "
- min thickness of lacing member! -
 $t_{min} = \frac{l_1}{40}$ $\rightarrow$ single
 $= \frac{l_1}{60}$ $\rightarrow$ double.
- min width:

nominal dia of rivet	
16 mm	50 mm
18 mm	55 mm
20 mm	60 mm
22 mm	65 mm

- It depends upon the nominal dia. of rivet.
- In case of welding, width of lacing bar is 50 mm

Er. Anjana Khamari prevent buckling of column component b/w lacing connection! —

$$\lambda_{\text{component}} \neq 50$$

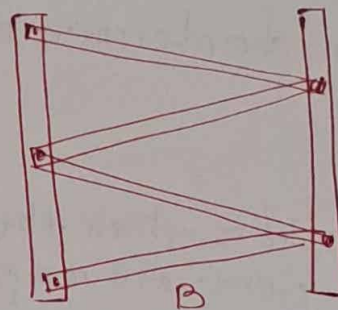
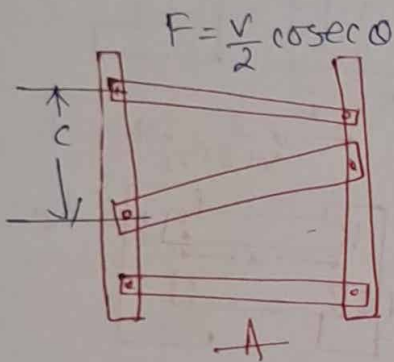
$$\neq 0.7 \lambda_{\text{column}}$$

For thick rivets! —

$$\lambda_{\text{component}} \neq 40$$

$$\neq 0.6 \lambda_{\text{column}}$$

- At the end of lacing system, at top & bottom, tie plates are provided (tie plate is called batten plate).
- these batten plate prevent distortion of built up columns.



$$F = \frac{2V}{N} \cot \alpha$$

$$F = V \cot \alpha$$

- Arrangement 'A' is better than B, because of one rivet fails, spacing of lacing member doesn't change in A while in B, spacing will be doubled. Hence there will be possibility of buckling of connection in B.

Forces in lacing members! —

- Lacing system is designed to resist a transverse s.f of $v = 2.5\%$ of column load.
- The transverse s.f v is shared by lacing system both side equally, so the transverse s.f on each lacing bar is $\frac{v}{2}$.

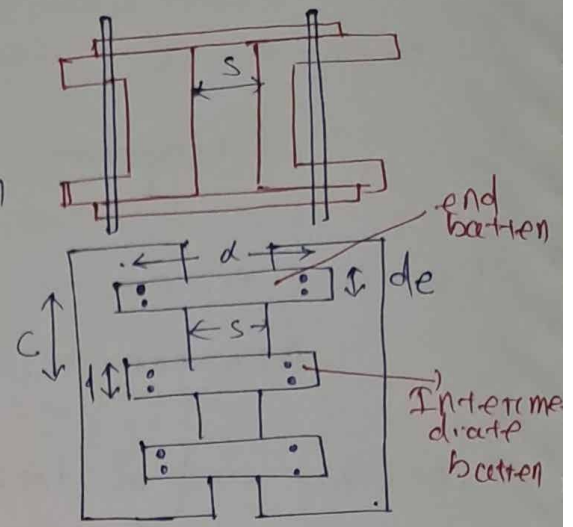
* 2 denotes no. of parallel plates.

* $F = \frac{v}{2 \sin \alpha}$ — single — two parallel force system
force in each lacing bar

* $F = \frac{v}{4 \sin \alpha}$ — double

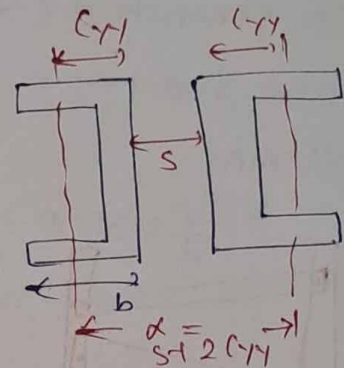
Battens

- It behave like very small beam member & s.t. BM.
- the eff. length of battened column should be $\uparrow$ by 10%.
- min^m no. of battens provided = 4
- provided batten on opposite faces such that one should be the mirror image of other.



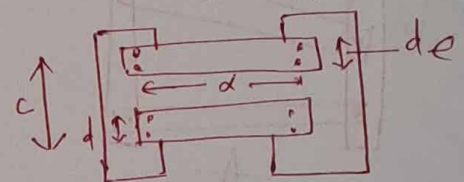
- eff. slenderness ratio,
 $\lambda = 1.10 \lambda_0$ ($\uparrow$ by 10% in battens)

$\lambda_0 \rightarrow$ max^m actual slenderness ratio



- eff. depth:—

- It should not be less than the distance betⁿ centroid component members. $d_e \geq \alpha$



- It should not be less than twice the width of one component in plane of battens (b).
 $d_e \geq 2b$.

- thickness of batten (t):— $t \geq \frac{\alpha}{50}$

- to prevent local buckling of individual component betⁿ the battens, following cond^s are specified:—

$$\frac{C}{r_{yy}} < 50$$

$$\frac{C}{r_{yy}} < 0.7 \lambda_{\text{column}}$$

- For intermediate batten,

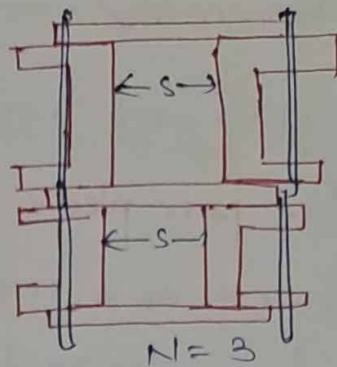
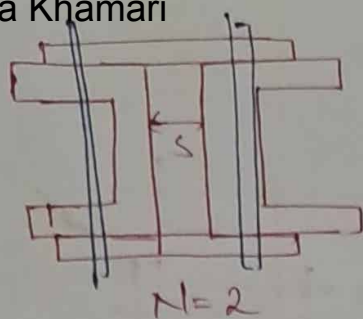
$$d_e > \frac{3}{4} \alpha$$

$$d_e > 2b$$

- For end batten,

$$d_e > \alpha$$

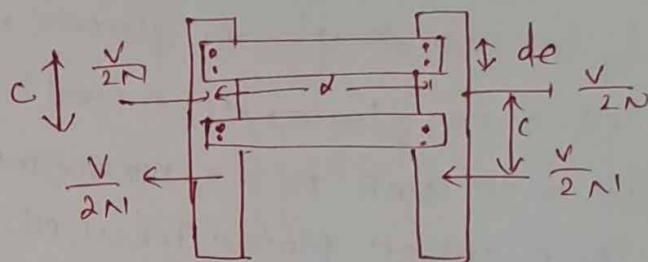
$$d_e > 2b$$



→ Transverse s.f. V is shared by parallel plates (N) equally
i.e. Transverse s.f. each batten = $\frac{V}{N}$

N = no. of parallel plates

- Batten should be designed to carry BM & SF arising from the transverse s.f. V , which is 2.5% of total axial load on comp. members.



- the transverse s.f. is equally divided in all the parallel plates N in which there are shear resisting elements such as battens or continuous plates battens.
- Battens should be able to resist the longitudinal shear & moment arising from transverse shear V .

$$\text{Longitudinal shear (V}_l\text{)} = \frac{Vc}{N\alpha}$$

V → Transverse s.f. → 2.5% of P

N → no. of parallel plates of battens.

$$\text{Longitudinal moment (M)} = \frac{Vc}{2N}$$

Column Splicing

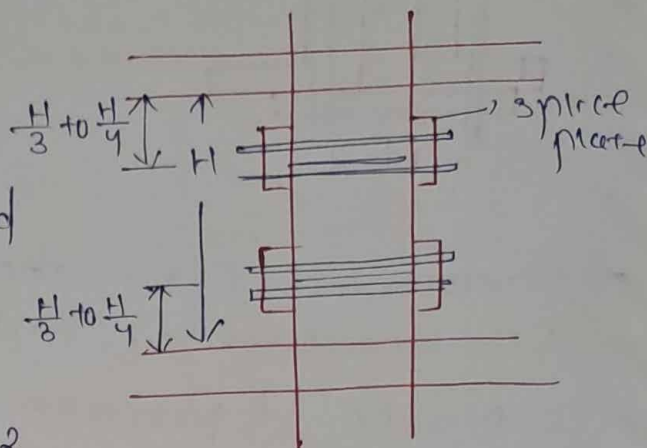
- Splicing of column is done to 1/3 the length of column.
- the most suitable location for column splicing is at a suitable location of $\frac{H}{3}$ to $\frac{H}{4}$ from the top & bottom level floor.
- when the column end are machined then it is assumed that 50% of load is transferred by direct bearing action & remaining 50% of the load is transferred through splice & its connection.

Er. Anjana Khamari $\frac{P}{2}$ → Bearing action

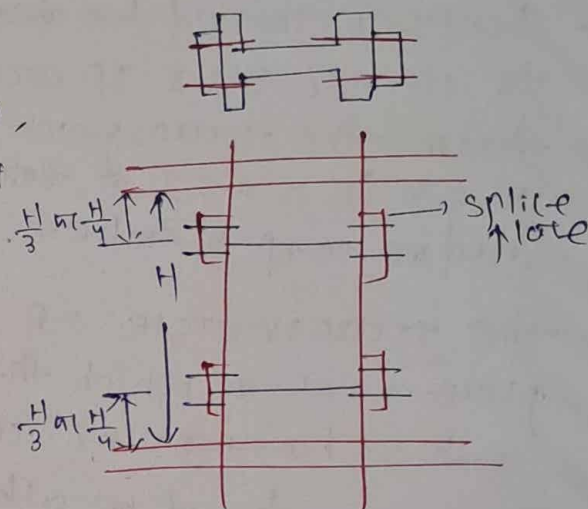
$\frac{P}{2}$ → splice end connection

$\frac{P}{4}$ → each splice per plate

- If a column is s.t. to a comp. load P , the $\frac{P}{2}$ is transferred by bearing action & remaining $\frac{P}{2}$ is taken by splicing plate, $\frac{P}{4}$ by each splicing plate (since 2 splicing plates are used).

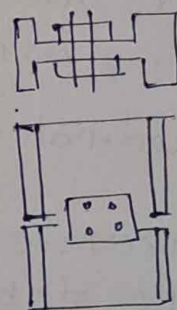


- If a column is s.t. moment M also, then splice plate must also resist additional force of $\frac{M}{H}$, so max force in splice plate's max load for each splice plate = $\frac{P}{4} + \frac{M}{H}$



NOTE

- If the column ends are not smooth, for complete bearing, entire load is assumed to be transferred to the bottom column through splice plate & connection only.
- Hence max force in each splice plate when column ends are not smooth.

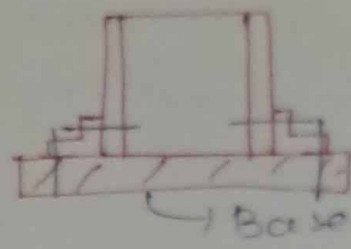


$\frac{P}{2}$ → each splice per plate
max load for " " " " = $\frac{P}{2} + \frac{M}{H}$

- If s.f. is also acting at a column splice, a web splice must be done, both side of the web as shown.
- the rivet in web splice are s.t. double shear & bearing but rivet in flange splice are s.t. single shear & bearing.

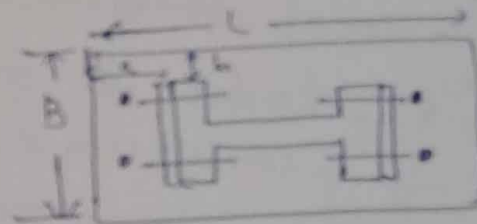
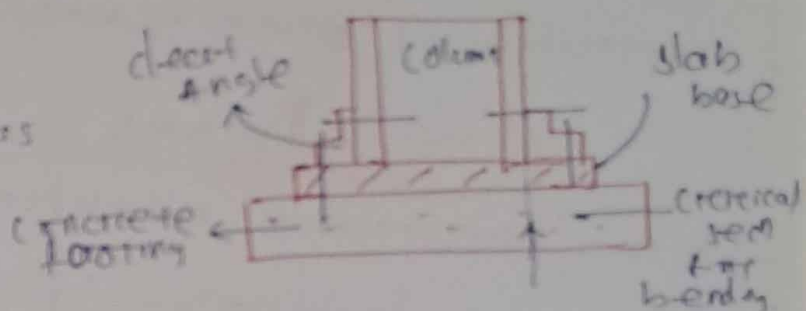
Slab Base

- It is a base plate used to reduce the bearing pr. on the concrete footing.
- It transfers the load to the concrete footing, preventing the punching shear of footing.
- If the column load is ~~more~~ less, slab base is used.
- If the " " " ~~more~~ heavy, then gusseted base is used.
- If the soil is weak, grillage foundation is used.



slab base

- permissible tensile stress of bolt used in column base is 120 MPa.
- In slab base, base plate & cleat angle are used.
- If column load is axial, then thickness of base plate is given by -



$$t = \sqrt{\frac{3W}{6bs}} \left(d^2 - \frac{b^2}{4} \right) \rightarrow \text{WSM}$$

$$t = \sqrt{\frac{2.5W}{6bs}} \left(d^2 - 0.3b^2 \right) \rightarrow \text{LSM}$$

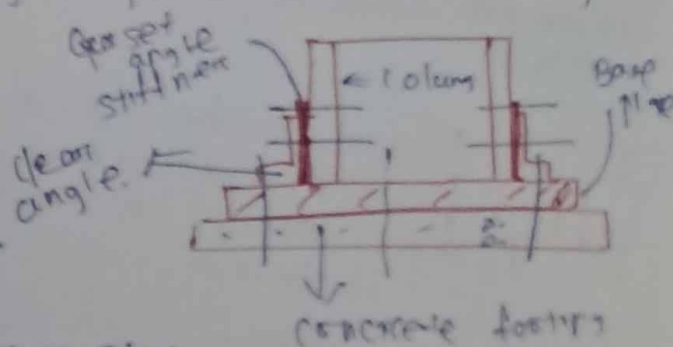
W → upward pr. on base plate in N/mm^2

a, b → greater & smaller projection of base plate beyond column edge.

$6bs$ → permissible bearing comp. stress in base plate.

Gusset Base

- Adopted when the load is large.
- Axial load accompanied by BM.
- Having eccentric loadings.
- Area can be ↑ by adding gusset plates.

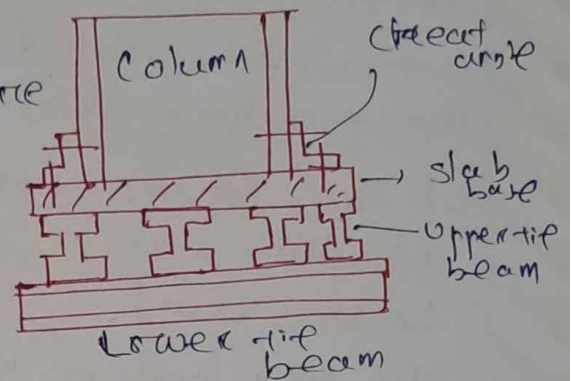


load is transferred to soil by fasteners.

- critical section for BM is at toe of gusset plate.
- core x kernel :- It is the small portion of cross section within which load is applied, tension will not be developed.

Spillage found

- Adopted when loads on columns are extremely heavy.
- the bearing capacity of soil for the area of gusset / slab is not enough.
- distribution area is very large.



Beams

- It is a structural member s.t. transverse load.

flexural formula :- $\frac{M}{I} = \frac{\sigma}{y} = \frac{E}{R}$

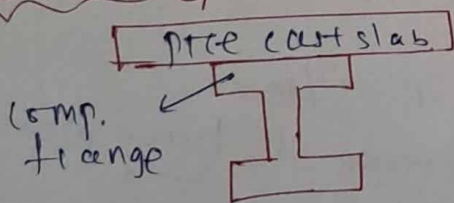
$R \rightarrow$ Radius of curvature

$\frac{1}{R} \rightarrow$ curvature.

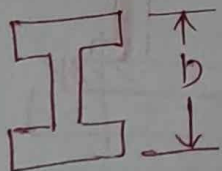
Moment is directly proportional to curvature.

$M \propto \frac{1}{R}$

Laterally unsupported beam (L.U.B.)



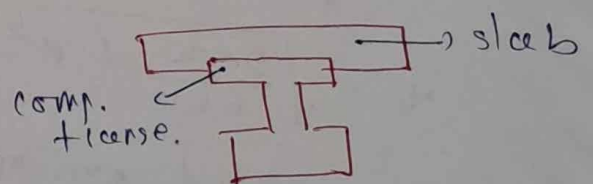
- If the comp. flange of beam is not restrained against lateral movement, then it is called as L.U.B or



In the dgn. of beam, we assume that the depth of web is resisting shear is taken as vertical depth of the beam.

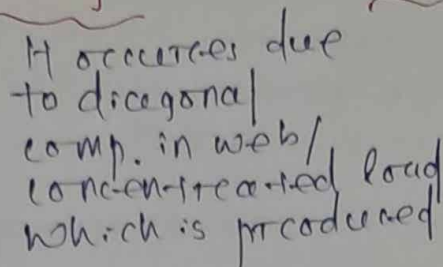
$\left[\tau_{va \text{ calculate}} = \frac{V}{Dtw} \right]$

Laterally supported beam

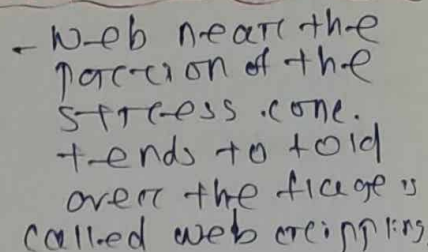


- If the comp. flange of beam is restrained against lateral movement, then it is called as laterally supported beam or laterally restrained beam.

web crippling / local buckling of web

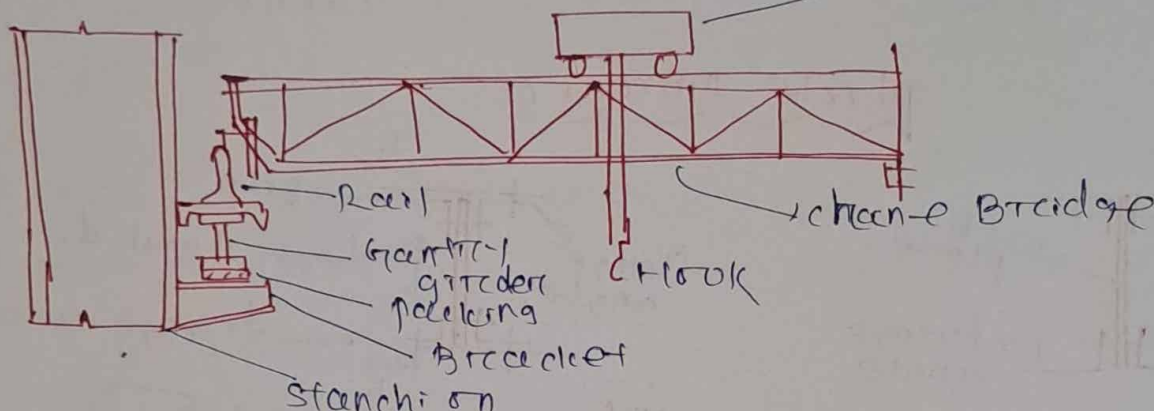


- If stress been too of filler weld.



- Developed due to large amount of bearding stress.
- Stress conc. occurs at the junction of web & fringe.

theolly otc eteab



It is s.t. $\leftarrow$ Gravity loads (i.e. DL + LL + wt. of creosoltruss + wt. of truss, etc).

- ii) Lateral load (due to starting or stopping of crabs)
- iii) Longitudinal " " " " " " " " " " " "

- these three loads are mutually $\perp$ to each other,
- Horizontal & vertical loads are applied simultaneously,
- allowable stress in garter girders are $\uparrow$ by 10%.

- Additional load due to impact.

— type of loading

Impact allowance

vertical bond

1. E.O.C

→ 25% max^m static wheel load

2. M.O.C

→ 10.1. " " " "

1. 15. 10. 11

→ 10% wt. of trolley & wt. lifted

2. M. O. C

5. 1. 11 11 11 11

Horizontal force along the rear $\rightarrow$ 5-1. of static wheel load.

Determinable stress in Girders/ girders

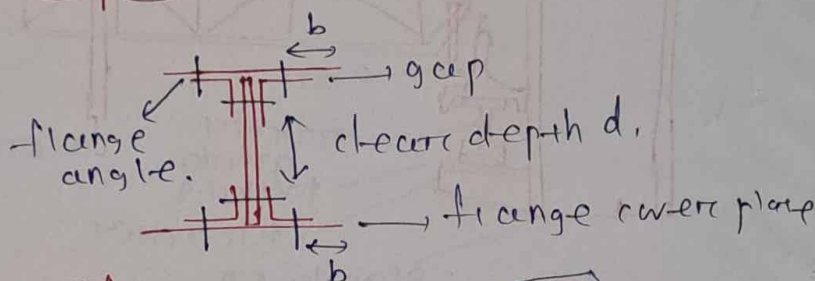
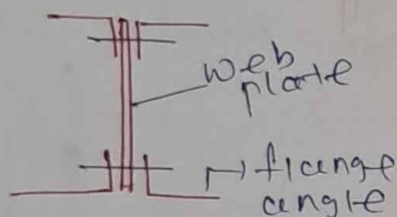
- these are laterally unsupported beams to carry heavy loads from place to place at the construction sites.

1. $\delta = \frac{\text{span}}{500} \rightarrow$ for manually operated crane.

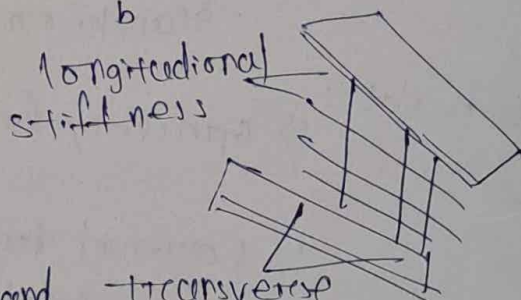
2. $\delta = \frac{\text{span}}{750} \rightarrow$ electrically operated crane capacity up to 50 T or 50 kN

3. $\delta = \frac{\text{span}}{1000} \rightarrow$ " " more than 50 T or 50 kN capacity

Plate Girders



- A plate Girder is essentially thought as flexural member whose cross secⁿ is composed of plate elements, flange plate, angle & web equivalent.



- A built up beam can't withstand applied load then plate girders are used.

- It consists of flange plate, flange angle & web plate.

- It consists of flange plate, flange angle & web equivalent.

- web equivalent is the web area embedded betⁿ two flange angle.

- In comp. zone flange, web equivalent is taken as $\frac{a_w}{6}$

or $\frac{a_w}{6}$

Tension Flange

- It consists of flange plate, angle & web equivalent.

- In tension zone, web equivalent is taken as

$\frac{a_w}{8}$

plate girder is assumed that entire S.F. is taken by web plate & BR is taken by flange (to ensure that web takes only S.F., gap of 5mm will be maintained betn flange plate & web plate so that direct bearing action betn flange plate & web plate is avoided).

- The load is transferred from flange plate to web plate through flange angles only.

- width of outstand in comp. flanges $\rightarrow b \nless 16t_f$
 $b \nless \frac{256t_f}{\sqrt{f_y}}$

- " " " tension " $\rightarrow b \nless 20t_f$

- Economical depth of web plate (which is corresponding to min^m wt. betn min^m cost).

$$d = 1.1 \sqrt{\frac{M}{6b_c \times t_w}}$$

- self wt. of plate girder is assumed as: -

$$w = \frac{w}{300} \text{ kN/m} \rightarrow \text{WSM}$$

$$= \frac{1.5w}{300} \text{ kN/m} \rightarrow \text{LSM} = \frac{w}{200} \text{ kN/m}$$

- If $\frac{d_1}{t_w} < 85$, web buckling due to shear will not happen, so stiffeners are not provided. the web will be unstiffed

- If $\frac{d_1}{t_w} > 85$, vertical " " provided to prevent buckling of web due to diagonal comp. which is developed due to S.F.

- If $\frac{d_1}{t_w} > 200$, Horizontal stiffeners are provided above NA as they prevent buckling web due to bending comp. stress.

- If $\frac{d_1}{t_w} > 250$, then additional horizontal stiffeners are provided along

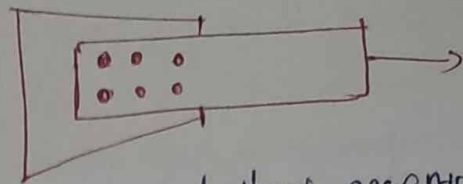
- If $\frac{d_1}{t_w} > 400$, then secⁿ must be redesigned.

- After providing all the stiffeners, lesser clear dimension of web panel should not exceed $180t_w$.

- Greater clear dimension of web panel $\nless 270t_w$.

Tension Members (tie)

— A structural member s.t. axial tension is called tension member or tie.



— the members & connections are so arranged that eccentricity in the connection & bending stress are not developed.

Types of failure

1. Gross secⁿ yielding —
Considerable deformation of the member in longitudinal dirⁿ may take place before it fractures, making the str. unserviceable. Hence we must also consider yielding on gross-secⁿ.

2. Net secⁿ rupture —
the fracture of the member occurs when the net cross-secⁿ of the member reaches ultimate stress.

3. Block shear failure —
A segment of block of material at the end of member shears out due to the possible use of high bearing strength of steel & high strength bolts resulting in smaller connection length.

Dgn. strength of TM —

1. Gross secⁿ yielding — $T_{dg} = \frac{f_y}{\gamma_{mo}} \cdot A_g$
 $\downarrow$ $\downarrow$
 dgn. strength Gross sectional area
 1.1 → partial safety factor

— When a TM is st. tensile force although the net cross-secⁿ yields 1st, the deformation within the length of connection will be smaller than the ' ' in the remainder of TM.
 — It is because the net area exist within the small length of member, most of the length of member will have an un-reduced cross-secⁿ, so attainment of yield stress on gross area will result in larger total elongation.

2. Net secⁿ rupture (fracture) —
 $T_{dn} = \frac{0.9 f_u}{\gamma_{m1}} \cdot A_n$
 $\downarrow$ $\downarrow$
 dgn. strength in rupture ultimate strength of material
 1.25 → est. net area of c/s

- For plates: -

- For shear yield & tension fracture: -

$$Tdb1 = \frac{f_y A_{vg}}{\sqrt{3} r_{m0}} + \frac{0.9 f_y A_{tn}}{r_{m1}}$$

- For tension yield & shear fracture: -

$$Tdb2 = \frac{f_y A_{tg}}{r_{m0}} + \frac{0.9 f_y A_{vn}}{\sqrt{3} r_{m1}}$$

Where,

A_{vg} → min^m gross area in shear along the line of force

A_{tn} → " net " " " " " " " " "

A_{tg} → " gross " " in tension

A_{vn} → " net " " " " " " " " "

Slenderness ratio in TM: →

- It is the ratio of its unsupported length 'L' to its least radius of gyration.

- Max^m slenderness ratio for tension member is given as:-

* A TM in which reversal of direct stress due to loads other than wind or seismic force occur. → 180

* A member normally acting as a tie in roof truss or a bracing system s.t. possible reversal of stresses resulting from the action of wind & earthquake forces. → 350

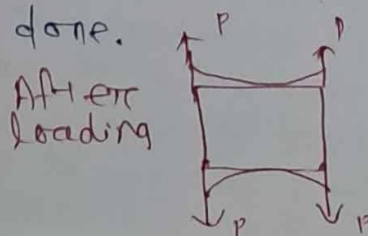
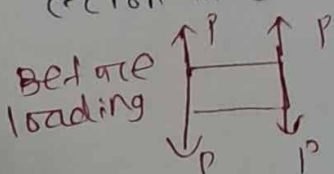
* Members always under tension (other than pre-tensioned members) → 400

SHEAR LEG

- Non uniform stretching of member due to tension is called shear leg.

- It reduce the efficiency of TM that are not connected to gusset plate.

- For reducing shear leg, lengthening of connections & reduction in efficiency is done.



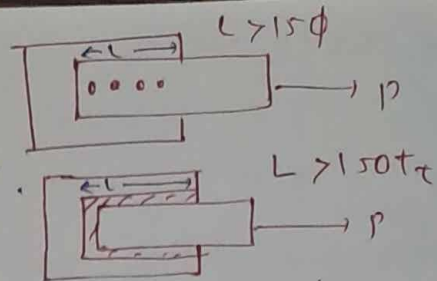
Increase in length reducing the efficiency.

LONG JOINT (LJ)

L = overlapping length.

If $L > 15\phi$ or $L > 150\text{mm}$ then it is called long joint.

- It is assumed that applied load is shared by all the rivets, but in LJ, outer rivet takes more load than the inner. So failure of rivets in long joints is sequential, beginning with those at the ends & progressing towards centre, this type of failure is termed as 'unbuttoning'.

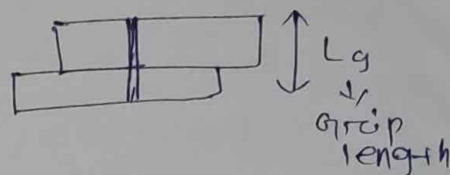


- If length of joint is more than efficiency of the TM would be less.

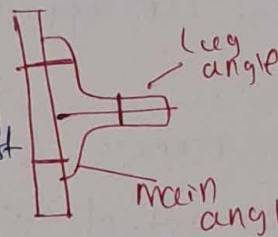
$$L_g = 5\phi \text{ (LSM)}$$

$$L_g = 8\phi \text{ (WSM)}$$

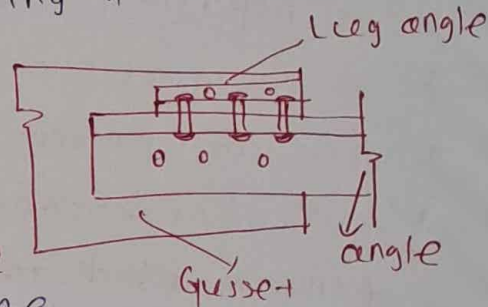
- If L_g increases then efficiency of joints decreases due to additional bending stress developing in rivets.

LEG ANGLES

- It is small piece of angle used to connect the outstanding leg of the structural member to the gusset plate.



- The purpose of leg angle is to reduce the length of connection to gusset plate & reduce the shear lag effect.

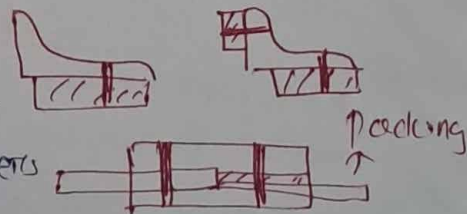


* shear lag effect is reduced by increasing the length of connection & by providing leg angles.

- If leg angle are used, the efficiency of TM increases.
- If length is increased, then shear lag effect is decreased but efficiency is also decreased. If leg angle is used then efficiency is increased & shear lag is reduced.

SPLICES

- They are used to joint two ends when a joint is to be provided, i.e., those place the members at the joint where it is cut.



- When a splice occurs in an angle, channel, tee or joint secⁿ, the force is received from the member through the connection on one side of joint & is transferred to the splice cover plate.
- The force is then carried through these covers across the joint & is transferred to other portion of member through the connections.

Local carrying capacity of tension members $P_t \rightarrow$ safe local carrying capacity

$$P_t = \sigma_{at} \cdot A_{net} \text{ (WSM)}$$

where,

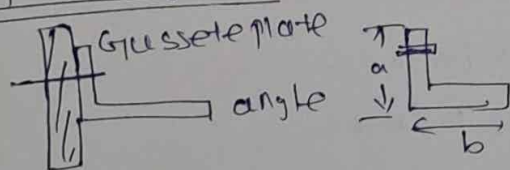
 $\sigma_{at} \rightarrow$ permissible axial tensile stress $= 0.6 f_y$ $A_{net} \rightarrow$ net effective c/s area.

$$P_t = \min \left\{ A_g \frac{f_y}{1.10} \mid A_{net} \frac{0.9 f_u}{1.25} \right\}$$

- To prevent fracture:-

$$A_{eff} = 0.9 A_{net}$$

$$P_t = A_{eff} \frac{f_u}{1.25}$$

For plate:-calculate of A_{net} i) chain riveting, $A_{net} = (B - nd)t$ ii) diamond " , $A_{net} = (B - d)t$ iii) staggered " , $A_{net} = (B - n_1 d + \frac{p_1^2}{4g_1} + \frac{p_2^2}{4g_2})t$ $n_1 \rightarrow$ no. of rivets along critical section $d \rightarrow$ gross dia. or hole dia. p_1 & $p_2 \rightarrow$ staggered pitch g_1 & $g_2 \rightarrow$ " gauge.For angles

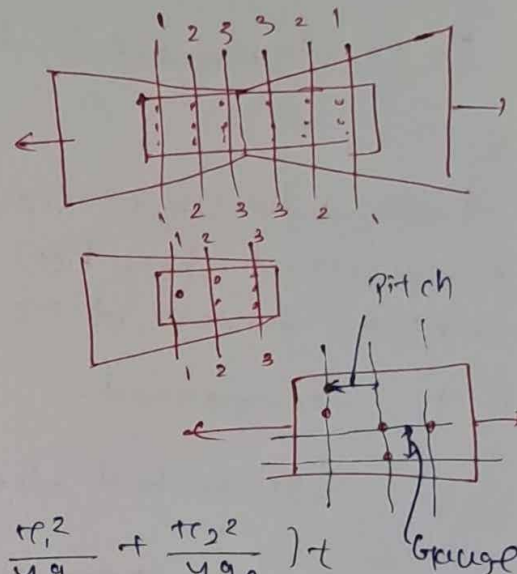
$$A_1 = (a - d - \frac{t}{2})t$$

$$A_2 = (b - \frac{t}{2})t$$

- calculation of A_{net} - for angle:- $A_{net} = (A_1 + K A_2)$

$$K = \frac{3A_1}{3A_1 + A_2}$$

shear leg effect

 $A_1 \rightarrow$ net area of connected leg $=$ gross area of " " -
area of rivet hole $A_2 =$ gross area of unconnected leg
outstand leg.- If two angles are placed back to back
& connected to both sides of gusset plate. $K=1$ then $A_{net} = (A_1 + A_2)$ - It is most efficient way of connecting, then local carrying capacity is max^m.- If the two angles don't have rivet then each angle behaves independently hence, $K = \frac{3A_1}{3A_1 + A_2}$ 

1. To find A_{net} required?

$$A_{net} \text{ required} = \frac{P}{\sigma_{at}}$$

2. ↑ A_{net} by 40 to 50% to get A_g required when riveting is done.

3. ↑ A_{net} by 20% to get A_g required when welding is done.

4. select a suitable secⁿ & find the no. of rivets required.

5. If $A_g \text{ provided} > A_g \text{ required}$, so dsgn. is safe.

Q

check whether single angle of 75 in welded steel is required that has area 475 mm^2 to be dsgn for axial tension force of 50 kN , $\sigma_{at} = 150 \text{ MPa}$.

$$A - A_{required} = \frac{P}{\sigma_{at}} = \frac{50000 \text{ N}}{150 \text{ N/mm}^2} = 333.33 \text{ mm}^2$$

$$A_{provided} = 475 \text{ mm}^2 > 333.33 \text{ mm}^2 \text{ (dsgn. safe)}$$

As per IS 800

- In case of single angles in tension connected by one leg only, the net eff. area = $a + \frac{b}{1 + (0.2)\frac{b}{a}}$

- eff. area of plate greater, in tension = $A_t + \frac{A_w}{8}$
in comp. = $A_t + A_w$

As per IS 800 for mild steel:

proportional limit $\rightarrow 190 - 220 \text{ N/mm}^2$

yield strength $\rightarrow 230 - 250 \text{ N/mm}^2$

Ultimate " $\rightarrow 410 - 530 \text{ N/mm}^2$

Fracture " $\rightarrow 250 - 300 \text{ N/mm}^2$

elongation at fracture $\rightarrow 23 - 35 \%$

Bearing stress $\rightarrow 0.75 f_y$

NOTE

- Vertical stiffeners are provided to prevent shear buckling of web.
- Horizontal stiffeners are provided to avoid comp. buckling.

Vertical stiffeners: —

- these are not designed as column.
- min spacing is $\frac{d_1}{3} = 0.33d$.
- max " " = $1.5d$.

Load bearing stiffeners: —

- they are designed as imaginary column with both end are fixed whose eff. length = $0.7l$.

SyllabusModule I

- Introduction, advantages/disadvantages of steel, rolled steel section, various types of loads, design philosophy.
- Limit state design method, limit state of strength and serviceability, probabilistic basis for design, riveted, bolted and pinned connections.
- Welded connections - assumptions, types, design of fillet welds, intermittent fillet weld, plug and slot weld, failure of welded joints vs bolted and riveted joints.

Module II

Tension members, types, net cross-sectional areas, types of failure, slenderness ratio, design of tension members, gusset plate.

Module III

- Compression members, effective length, slenderness ratio, types of cross section, classification of cross section.
- Design of axially loaded compression members, lacing, battening, design of column base and foundation bolts.

Module IV

Design of beams, types of I/I, lateral stability of beams, lateral torsional buckling, bending and shear strength, web buckling and web crippling, deflection, design procedures.

Module V

Plate girders - various elements and design of components, eccentric and moment connections, roof trusses.

Limit state design of steel structure by S.K Duggal

IS 800:2007

1. Introduction

The design of steel structure is based on the limit state design method. The limit state design method is a design method in which the structure is designed such that it will not reach a limit state of failure under the design loads. The limit state design method is based on the concept of safety and reliability. The design of steel structure is based on the limit state design method. The limit state design method is a design method in which the structure is designed such that it will not reach a limit state of failure under the design loads. The limit state design method is based on the concept of safety and reliability.

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5. Design of steel structure

The design of steel structure is based on the limit state design method. The limit state design method is a design method in which the structure is designed such that it will not reach a limit state of failure under the design loads. The limit state design method is based on the concept of safety and reliability.

Ingredients of Cement

- 1/ Lime
- 2/ Silica - 20%
- 3/ Alumina
- 4/ Gypsum
- 5/ Iron oxide
- 6/ Magnesia
- 7/ Sulphur Trioxide
- 8/ Soda and potash

Introduction

- A steel structural is an assemblage of a group of members expected to sustain their share of applied forces and to transfer them safely to the ground.
- Depending upon the orientation of the member in the structure and its structural use, the member is subjected to forces either axial, bending or torsion or a combination thereof.
- Axial load can be either tensile or compressive and accordingly the members are called tension members or compression members.

Advantages of Steel

- 1/ Steel members have high strength per unit weight.
- 2/ Steel being a ductile material does not fail suddenly but gives visible evidence of impending failure by large deflections.
- 3/ Structural steels are tough i.e. they have both strength and ductile.
- 4/ Being light steel members can be conveniently handled and transported.
- 5/ Properly maintained steel structures have a long life.
- 6/ The properties of steel mostly do not change with time.
- 7/ Additions and alterations can be made easily to steel structures.
- 8/ They can be erected as a faster rate.

10) Steel has the highest scrap value amongst all building materials.
10) Steel is the ultimate recyclable material.

Disadvantages of steel

- 1) Steel structures when placed in exposed conditions are subjected to corrosion.
- 2) The use of weathering steels however in suitable applications may eliminate the requirement of frequent painting.
- 3) Steel structures need fireproof treatment which increases cost.
- 4) Fatigue of steel is one of the major drawbacks. It involves a reduction in the strength when steel is subjected to large number of stress reversals and even to a large number of variations of tensile stress.
- 5) At the place of stress concentration in the steel section under certain conditions the steel may lose its ductility.

2/1/25

Tension Member

The axial load can be tensile members is called tension member.

Ex: tie

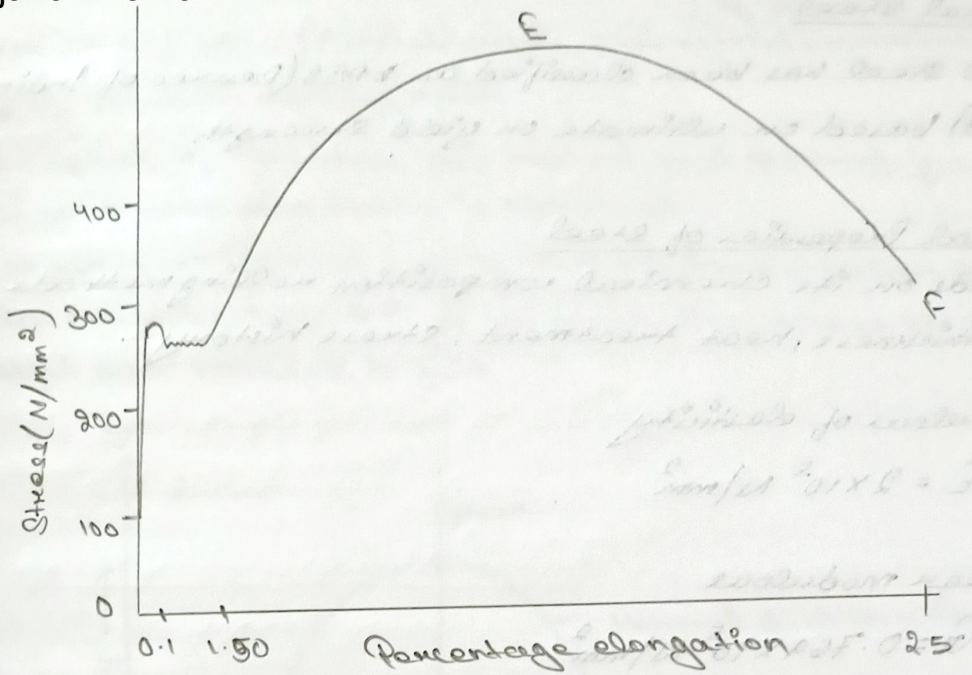
Compression Member

The axial load may be compressive member is called compression member.

Ex: → Street
Column

Design of Structural elements

The position of elements i.e. beams, columns, trusses, purlins etc are used to planning the architecture design of buildings.



(Stress strain curve of mild steel)

Properties of steel

- 1/ Carbon
- 2/ Sulphur
- 3/ Phosphorus
- 4/ Manganese
- 5/ Silicon

Structural Steel

Structural steel has been classified as SSS (Source of Indian standard) based on ultimate or yield strength.

Mechanical Properties of steel

It depends on its chemical composition, rolling methods, rolling thickness, heat treatment, stress history.

① Modulus of elasticity

$$E = 2 \times 10^5 \text{ N/mm}^2$$

② Shear modulus

$$G = 0.769 \times 10^5 \text{ N/mm}^2$$

③ Poisson's ratio (μ)

a) Elastic range = 0.3

b) Plastic range = 0.5

④ Coefficient of thermal expansion

$$12 \times 10^{-6} / ^\circ\text{C}$$

22/125

Ultimate Strength (UTS)

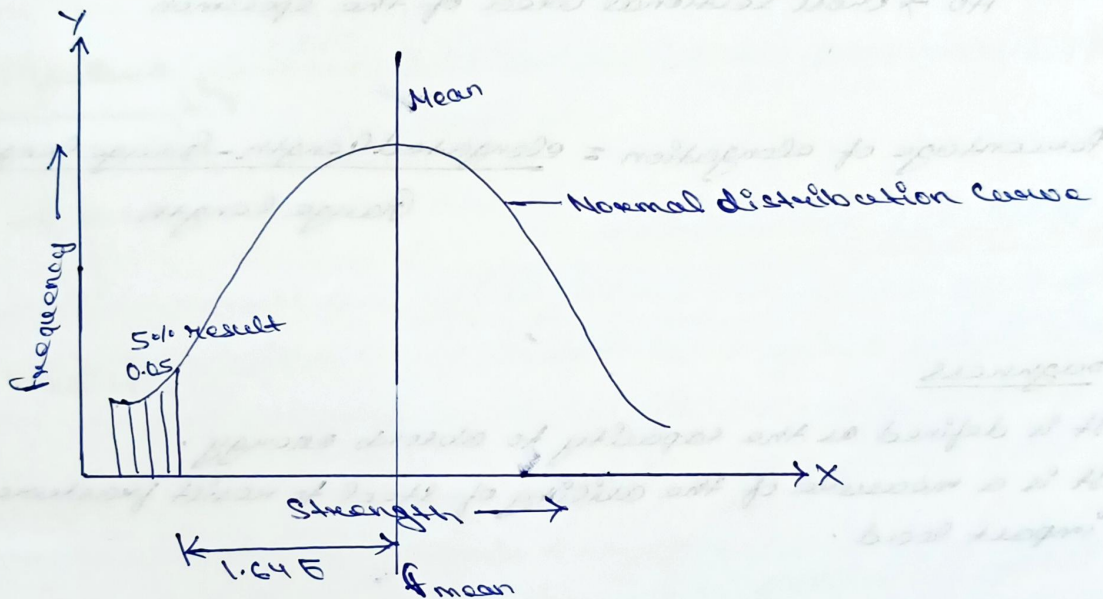
$$\text{UTS} = \frac{\text{Ultimate tensile load}}{\text{Cross sectional area}}$$

- It is subjected to tension, the area of cross-section of the specimen decreases and the ultimate strength stress would be ultimate tensile load divided by reduced area of cross section.

Characteristic strength

of steel is

- As per IS 800, the characteristic strength is determined from test of steel in rolling mill.
- If a number of specimen are tested and plotted for strength, a normal distribution curve is obtained.
- The characteristic strength is the minimum value below which not more than 5% of corresponding stress of specimens tested are expected to fail.



$$\text{Characteristic strength, } f_{ck} = f_{\text{mean}} - 1.645$$

where,

σ = Standard deviation

$$= \frac{\sum (f_{\text{mean}} - f)^2}{(n-1)0.5}$$

where,

n = no. of specimens

Ductility

- It is another important properties of steel.
- It is defined as the capacity of the structure or its members to undergo large in elastic deformation without significant loss of strength or stiffness.

$$\text{Gauge length} = 5.65 \sqrt{A_0}$$

where,

A_0 = cross sectional area of the specimen

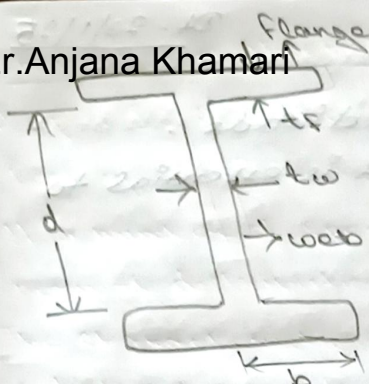
$$\text{Percentage of elongation} = \frac{\text{elongated length} - \text{Gauge length}}{\text{Gauge length}} \times 100$$

Toughness

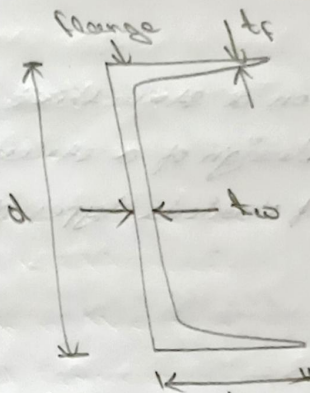
- It is defined as the capacity to absorb energy.
- It is a measure of the ability of steel to resist fractured under impact load.

Rollled Steel Section

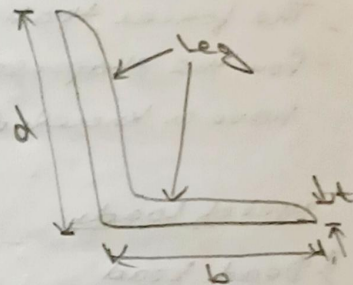
- 1) I Section
- 2) Channel Section
- 3) Angle Section
- 4) T - Section
- 5) Tube Section
- 6) Flat Section
- 7) Plate Section
- 8) Sheet Section
- 9) Bar Section
- 10) Strip Section



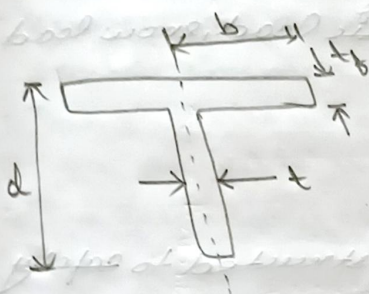
(I-section)



(Channel section)



(Angle section)



(T section)

- Load
- The forces that act on a structure is called loads.
 - For the safe design of a structure it is essential to have a knowledge of various types of loads.

Types of Loads

- 1) Dead Load
- 2) Live Load $\rightarrow$ earth pressure, water current load, impact load, Thermal loads etc.
- 3) Environmental Loads $\rightarrow$ Wind load, ^{Seismic} Seismic load, snow load, rain load

Basic Design of Structure

Steel structure should be design and constructed to safely satisfy the design requirements for stability, strength, serviceability, brittle fracture, fatigue, fire and durability with due to economy.

Design Philosophy

- 1) Initial yielding
- 2) Full width yielding
- 3) Tensile strength
- 4) Critical buckling
- 5) Maximum deflection permitted
- 6) Stress concentration
- 7) Fatigue
- 8) Brittle fracture

- * Working stress method (elastic)
- * Limit design method (Plastic)
- * Limit state method

Elastic Method

- It is the elastic method of design.
- The correct combination of working load is proportional to working stresses.
- The factor of safety is defined as

$$FOS = \frac{\text{Working Stress}}{\text{Yield Stress}} \times \frac{\text{Yield Stress}}{\text{Working Stress}}$$

- The analysis methods are based on assumptions and do not give the exact stresses.
- Structural members may temporarily be overloaded under certain circumstances.
- The stresses due to fabrication and erection are not considered in the design of ordinary structures.
- The secondary stresses may be appreciable.
- Underestimation of the future live load.
- Stress concentrations.
- Unpredictable natural calamities.

Plastic Method

- Steel is a ductile material and the stress strain curve obeys the load over the structure.
- The plastic range means large strain.

Limit State Method

- It is similar to plastic design which considers most critical limit state and serviceability (Design action $\leq$ design strength).

Q. The yield strength for a mild strength specimen was found to 250 N/mm^2 . Taking a factor of safety of 2, find out the working stress.

Solⁿ

Given data:-

For mild steel,

$$\text{Yield strength} = 250 \text{ N/mm}^2$$

$$\text{FOS} = 2$$

$$\text{Working stress} = \frac{\text{Yield strength}}{\text{FOS}}$$

$$= \frac{250 \text{ N/mm}^2}{2}$$

$$= 125 \text{ N/mm}^2$$

Q. A tie bar $50 \text{ mm} \times 8 \text{ mm}^2$ is to carry a load of 20 kN. A specimen of the same quality steel of cross sectional area 250 mm^2 was tested in the laboratory. The maximum load carried by the specimen was 125 kN. Find the ultimate tensile strength factor of safety in the design and the gauge length.

Solⁿ

Given data:-

Ultimate tensile strength for the steel

$$= \frac{\text{maximum load}}{\text{Cross-sectional area}}$$

$$= \frac{125 \times 1000}{250}$$

$$= 500$$

$$= 500 \text{ N/mm}^2$$

Plastic Analysis and Design

- Steel has unique physical property, ductility because of which it is able to absorb large deformation beyond the elastic limit without fracture.

- Plastic method of design are

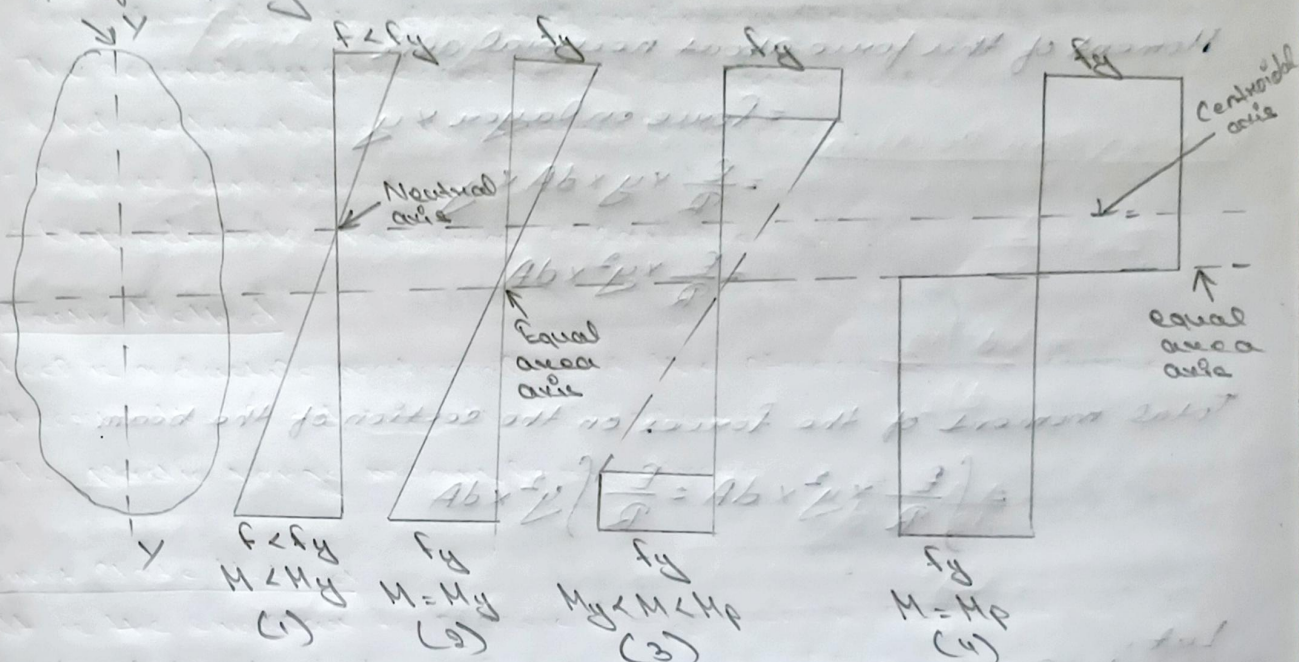
* Limit design

* Collapse method of design

* Ultimate design

Bending of Beams

Axis of symmetry



Development (in stages) of full plasticity of a beam section

$$A_b \times \frac{f}{2} = A_p \times \frac{f_y}{2}$$

Moment of Resistance

Due to pure bending, the layers above the neutral axis are subjected to compressive stresses whereas the layers below the neutral axis are subjected to tensile stresses. Due to these stresses, the forces will be acting on the layers. These forces will have moment about the neutral axis. The total moment of these forces about the neutral axis for a section is known as moment of resistance of that section.

$$\text{Force on layer} = \frac{E}{R} \times y \times dA$$

Moment of this force about neutral axis

$$= \text{force on layer} \times y$$

$$= \frac{E}{R} \times y \times dA \times y$$

$$= \frac{E}{R} \times y^2 \times dA$$

Total moment of the forces on the section of the beam.

$$= \int \frac{E}{R} \times y^2 \times dA = \frac{E}{R} \int y^2 \times dA$$

Let,

M = External moment applied on the beam section.

For equilibrium the moment of resistance offered by the section should be equal to the external bending moment.

$$\therefore M = \frac{E}{R} \int y^2 \times dA$$

Let $\int y^2 \times dA$ represents the moment of inertia of the area of the section about the neutral axis.

Let the moment of inertia be I .

$$\therefore M = \frac{F}{R} \times I \quad \text{or} \quad \frac{M}{I} = \frac{F}{R}$$

From the equation (7.2), we have

$$\frac{\sigma}{y} = \frac{F}{R}$$

$$\frac{M}{I} = \frac{\sigma}{y} = \frac{F}{R} \quad (\text{Bending equation})$$

In this equation, the different quantities are expressed in consistent units as given:

M is expressed in Nm ; I in mm^4

σ is expressed in N/mm^2 ; y in mm

F is expressed in N/mm^2 ; R in mm

3/2/25

Shape Factor (S)

It is defined as the ratio of the plastic moment and the yield moment of the section.

$$S = \frac{M_p}{M_y}$$

$$\Rightarrow S = \frac{F_y \cdot Z_p}{F_y \cdot Z_e}$$

$$\Rightarrow \boxed{S = \frac{Z_p}{Z_e}}$$

where,

Z_e = Elastic modulus

is defined as the first moment of area.

$$Z_e = \frac{I}{Y}$$

where,

I = Moment of Inertia (Second moment of area)

Y = Distance of the extreme fibre distance from the neutral axis.

Z_p = Plastic modulus (It is the combine statistical moment of the cross sectional area above and below the equal area axis of a completely yield section)

Rectangular Section

$$Z_e = \frac{I}{Y}$$

$$= \frac{bd^3/12}{d/2}$$

$$= \frac{bd^3}{12} \times \frac{2}{d}$$

$$= \frac{bd^2}{6}$$

$$Z_p = \frac{bd^2}{4}$$

$$S = \frac{Z_p}{Z_e}$$

$$= \frac{bd^2/4}{bd^2/6}$$

$$= \frac{bd^2}{4} \times \frac{6}{bd^2}$$
$$= 1.5$$

$$\frac{9/4}{3/4} = 3$$

$$\frac{9.5 \times 2}{2.5 \times 1.7} = 2.4$$

$$\frac{9.5}{2.5} = 3.8$$

It is defined as the ratio of the collapse load to the working load.

$$F = \frac{P_u}{P_w}$$

$$= \frac{M_u}{M_w}$$

$$= \frac{f_y Z_p}{f_z e}$$

$$F = \frac{f_y}{f} \cdot \frac{S}{f}$$

where,

$$\frac{f_y}{f} = \text{Factor of Safety}$$

$$F.O.S = \frac{f_y}{f}$$

$$= \frac{f_y}{0.66 f_y} = 1.515$$

$$(\because f = 0.66 f_y)$$



Permissible bending stress

Rectangular Section

$$F = 1.515 \times 1.5$$

$$= 2.2725$$

$$\leq 2$$

* For rectangular section:-

$$S = 1.5$$

$$F = 2$$

* For I section:-

$$S = 1.12$$

$$F = 1.7$$

Probabilistic Basis for design for Connection

There are three types of connections:-

- 1) Riveted Connection
- 2) Bolted Connection
- 3) Pinned Connection

1) Riveted Connection



a) Square

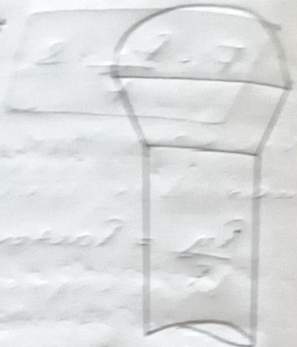


b) Conical



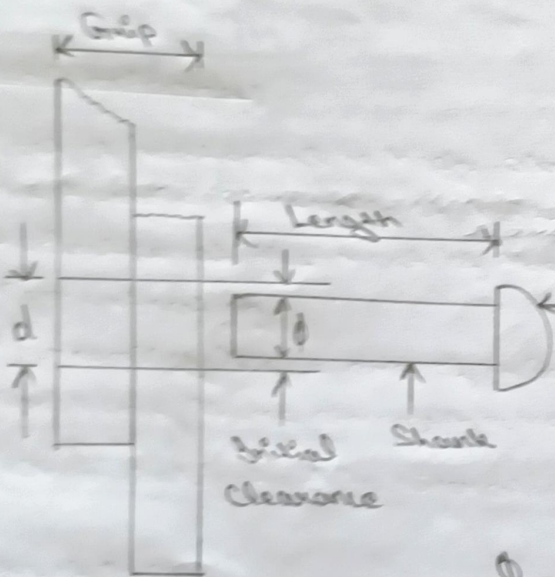
c) Flat

Countersunk



d) Round

Countersunk



e)

Φ - Nominal diameter of rivet
 d - Gross diameter of rivet

$P_1 = 8$
 $F_1 = 7$

A rivet is made of a round ductile steel bar piece (mild or high tensile) called shank, with a head at one end.

Description

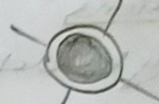
Shop rivets

Field rivets

Round head both sides



Countersunk near sides



Countersunk four sides



Countersunk both sides



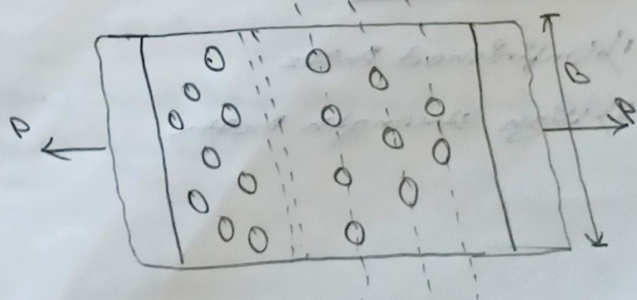
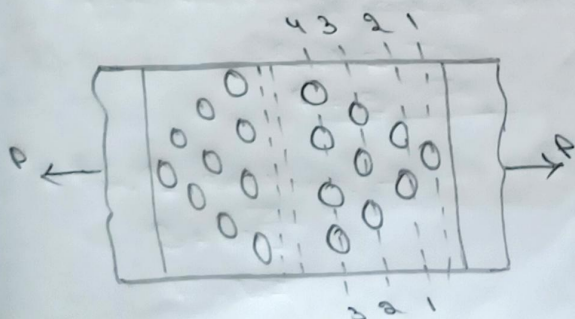
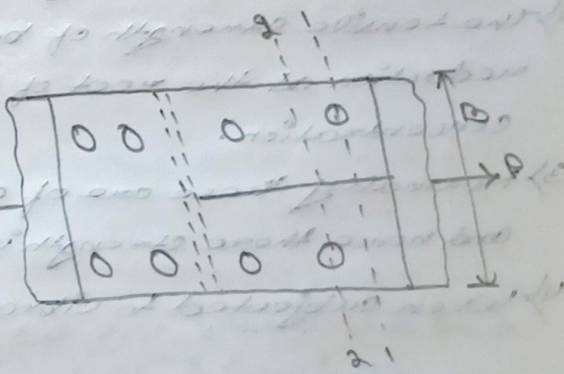
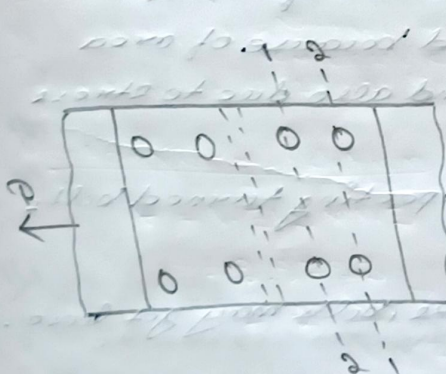
Patterns of Rivetted Joints

1/ Chain

2/ Staggered chain

3/ Diamond

4/ Staggered diamond



Design of Riveted Joint

- 1) The diameter of rivet to be used in the calculation is diameter of hole whereas for bolted connections it is the nominal diameter of bolt in case the holes are drilled.
- 2) The design stresses are slightly different for bolts.

Bolted Connections

The bolt may be defined as a metal pin with a head at one end and a shank threaded at the other end to receive a nut.

Advantages

- 1) The erection of the structure can be speeded up.
- 2) Less skilled persons are required.
- 3) The overall cost of bolted construction is cheaper than that of riveted construction because of reduced labour and equipment costs and the smaller number of bolts required resisting the same load.

Disadvantages

- 1) Cost of material is high, about double that of rivets.
- 2) The tensile strength of bolt is reduced because of area reduction at the root of the thread and also due to stress concentration.
- 3) Normally these are of a loose fit excepting turned bolts and hence their strength is reduced.
- 4) When subjected to vibrations or shocks, bolts may get loose.

Types of Bolts

- 1) Unfinished Bolts
- 2) High Strength Bolts

Unfinished bolts are called ordinary, common, rough or black bolts. These are used for light structures subjected to static loads and for secondary members such as purlins, bracing, roof trusses etc.

2) High Strength Bolts

The high strength bolts are made from base of medium carbon heat treated steel and from alloy steel.

Advantages

- HSTB bolts provide a rigid joint. There is no slip between the elements connected.
- Large tensile stresses are developed in bolts, which in turn provide large clamping force to the element connected.
- There is no stress concentration in holes, and therefore the fatigue strength is more.
- Few persons are required to make the connections, their cost is reduced.
- Noise nuisance is not there and there is no danger of tearing of the sheet.
- Alterations can be done easily.

Types of Bolted Joints

1) Lap Joint

2) Butt Joint

1) Lap Joint

The two members to be connected are overlapped and connected together. Such a joint is called lap joint.

2) Butt Joint

The two members to be connected are placed end to end. Such a joint is called butt joint.

- Depending upon the type of bolts - ordinary or high strength bolts - the load transfer from one connected part to another may be by shear and bearing or by friction.
- The former being called bearing type connection and the latter the slip-critical or slip-resistant connection.
- The connection made with high-strength bolts may, however, be slip-resistant or bearing type.

Failure of Bolted Joints

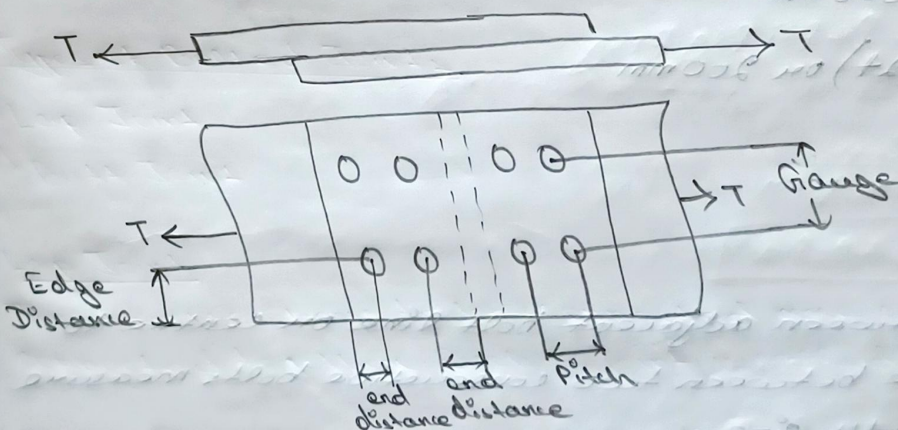
- 1) Shear failure of bolts
- 2) Bearing failure of bolts
- 3) Tension failure of bolts
- 4) Tension or tearing failure of bolts
- 5) Block Shear failure.

Shear failure of bolts

&

6/2/25

Specification for bolted joints



(Double cover butt joint)

Diameter of Bolt

The range diameter of bolt are favourable in connection where shear governs because, the bolt capacity in shear is varies as square of the bolt diameter.

Spacing of Bolt hole

1) Pitch (P)

It is the distance between the centre of two consecutive bolts measured along a row of the column.

* Minimum Pitch

To prevent bearing failures of members between the two bolts. Less than 2.5 times of the nominal diameter of the bolt.

* Maximum Pitch

To reduce the length of the connection and gusset plate.

Limit of Pitch

1) $\nless 16t$ or 200 mm (Tension members)

$\nless 12t$ or 200 mm (Compression members)

2) $\nless 32t$ or 300 mm

3) $\nless (100\text{ mm} + 2t)$ or 200 mm

4) $\nless 750$ mm

Gauge (g)

The distance between adjacent bolt line or centre to centre distance between two consecutive bolts measured along the width size.

Types of Connection

- 1) Shearing strength of bolts
- 2) Bearing strength of bolt
- 3) Tensile strength of bolt

1) Shearing strength of bolt

The nominal shear capacity of bolt

$$V_{nb} = \frac{f_{ub}}{\sqrt{3}} (n_n A_{nb} + n_s A_{sb})$$

The nominal shear capacity of bolt for long joint will be less i.e.

$$V_{nb} = \frac{f_{ub}}{\sqrt{3}} (n_n A_{nb} + n_s A_{sb}) P_{gj} P_{lg} P_{pg}$$

where,

V_{nb} = Nominal shear capacity of the bolt

f_{ub} = Ultimate tensile stress of the bolt

n_n = Number of shear planes with threaded intersecting the shear plane.

n_s = Number of shear plane without threaded intersecting the shear plane

A_{nb} = Net tensile stress area

A_{sb} = Nominal shank area

n = Number of shear plane

P_{gj} = A reduction factor to allow for the overloading of the end ~~joint~~^{bolt} that occurs in longer connection.

P_{lg} = A reduction factor to allow for the effect of the large girth length.

P_{pg} = A reduction factor to account for packing plates in excess of 36 mm

Bolt diameter (mm), d	12	16	20	22	24	27	30	36
Area (mm ²)	84.3	157	245	303	353	459	561	817

8/2/25

For the safety of joints in shear, the strength of bolt V_{sb} .

$$V_{sb} \leq \frac{V_{sheb}}{Y_{mb}}$$

where,

Y_{mb} = Partial safety factor for the material of bolt.

$$V_{sb} = \frac{V_{sheb}}{Y_{mb}}$$

$$= \frac{f_{ub}}{\sqrt{3} Y_{mb}} \times (n_n A_{nb} + n_s A_{sb}) P_{ej} P_{eg} P_{phg}$$

For 4.6 grade steel bolt,

$$f_{ub} = 400 \text{ MPa}$$

$$V_{sb} = \frac{400}{\sqrt{3} \times 1.25} \times (n_n A_{nb} + n_s A_{sb}) P_{ej} P_{eg} P_{phg}$$

$$= 184.75 A_e P_{ej} P_{eg} P_{phg}$$

where,

A_e = effective area

$$\Rightarrow A_e = n_n A_{nb} + n_s A_{sb}$$

For bolt in double shear,

$$V_{sb} = 2 \times 184.75 A_e P_{ej} P_{eg} P_{phg}$$

Reduction Factor for Long Joint (ϕ_{lj})

Er. Anjana Khamari

- When the length of the joint exceeds $15d$ in the direction of the load the shear capacity of the joint is reduced.

$$\phi_{lj} = 1.075 - \frac{l_j}{200d} \quad (\text{for } 0.75 \leq \phi_{lj} \leq 1.0)$$

Where,

l_j = length of the joint (The diameter between the 1st and last row of bolt in a joint measure in the direction of load transfer)

* The reduction factor = 1

Reduction Factor for Large Grip Length (ϕ_{lg})

- When the grip length of the bolt increases, the bolt is subjected to a greater bending moment due to shear force acting on its shank.

$$\phi_{lg} = \frac{2d}{3d + l_g}$$

Where,

l_g = Grip length

Reduction Factor for Packing Plates (ϕ_{pkg})

When the packing plates are more than 6mm in thickness, the shank of the bolt is subjected to bending which affects the nominal shear capacity of the bolt.

$$\phi_{pkg} = (1 - 0.0125 t_{pkg})$$

Where,

t_{pkg} = thickness of the thinner packing plate in mm.

Bearing Strength of Bolt

Nominal bearing strength of bolt,

$$V_{npb} = 2.5 k_b d t f_u$$

Where,

$$k_b = \text{smaller of } \left\{ \begin{array}{l} \frac{e}{3d_o} \\ \frac{p}{3d_o} - 0.25 \\ \frac{f_{ub}}{f_u} \\ 1.0 \end{array} \right.$$

Where,

 d_o = diameter of hole e, p = end and point distance of the fastener along bearing direction. f_{ub} = Ultimate stress of bolt f_u = Ultimate tensile stress of the plate in Mpa d = Nominal diameter of the bolt in mm t = aggregate thickness

For the safety of the joint in bearing,

$$V_{pb} \leq \frac{V_{npb}}{\gamma_{mb}}$$

Where,

 γ_{mb} = the partial safety factor for material of bolt
= 1.25

$$\therefore V_{pb} = 2.5 k_b$$

$$V_{pb} = 2.5 k_b d t \frac{f_u}{\gamma_{mb}}$$

Tensile Strength of Bolt

The nominal capacity of bolt,

$$T_{nb} = 0.9 f_{ub} A_{nb}$$

$$< f_{yb} A_{sb} \frac{V_{mb}}{V_{mo}}$$

Where,

f_{ub} = ultimate tensile stress of bolt

f_{yb} = yield stress of bolt

A_{nb} = net tensile stress area of bolt

A_{sb} = shank area of bolt

The bolt is safe in tension if the factored tension force,

$$T_{db} \leq \frac{T_{nb}}{V_{mb}}$$

Where,

V_{mb} = the partial safety factor for material of bolt
= 1.25

V_{mo} = Partial safety factor for material resistance governed by yielding = 1.10

$$T_{db} = 0.9 \frac{f_{ub}}{V_{mb}} A_{nb}$$

Tensile Strength of Plate

Net area $A_n = (B - nd_n)t$, for chain bolting

For staggered bolting,

$$A_n = \left[B - nd_n + \sum_{i=1}^m \frac{P_{si}^2}{4g_i^2} \right] t$$

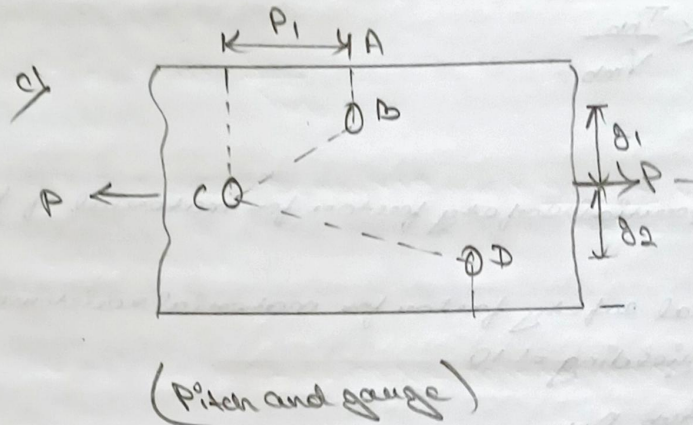
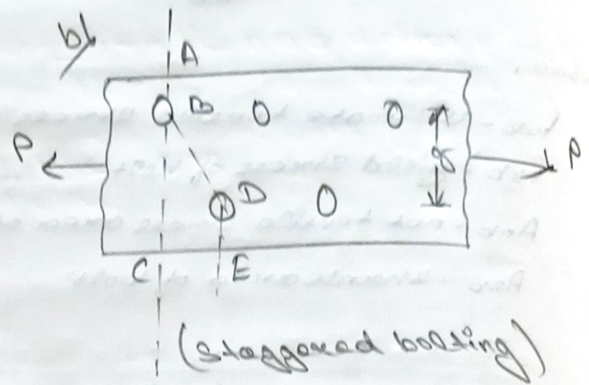
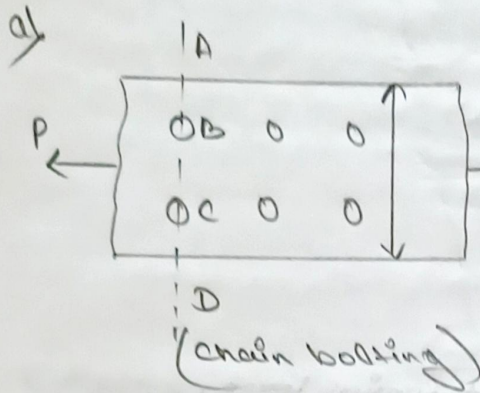
The tensile strength of the plate is given by

$$T_{nd} = 0.9 A_n \frac{f_u}{V_{ml}}$$

f_u = the ultimate stress of material in MPa

A_n = the net effective area in mm^2

γ_{mb} = partial safety factor = 1.25



Strength and Efficiency of the Joint

Efficiency of a bolted joint, (η)

(η) is also called the percentage strength of the joint

$$\eta = \frac{\text{Strength of bolted joint / Pitch length}}{\text{Strength of solid plate / Pitch length}} \times 100$$

Q) Calculate the strength of a 20 mm diameter bolt of grade 4.6 for the following cases. The main plates to be jointed are 12 mm thick.

a) Lap Joint

b) Single cover butt joint: the cover plate being 10 mm thick.

c) Double cover butt joint: each of the cover plate being 8 mm thick

Soln

Given data:

For grade 4.6,

$$f_{ub} = 400 \text{ MPa (for bolt)}$$

For Fe 410 grade of steel,

$$f_u = 410 \text{ MPa (for steel)}$$

$$\gamma_{mb} = 1.25 \text{ (partial safety factor for bolt)}$$

Diameter of bolt, $d = 20 \text{ mm}$

$$A_{nb} = 245 \text{ mm}^2$$

a) For Lap joint:

Strength of bolt for single shear,

$$V_{sb} = A_{nb} \frac{f_{ub}}{\sqrt{3} \gamma_{mb}}$$

$$= 245 \text{ mm}^2 \times \frac{400 \text{ MPa}}{\sqrt{3} \times 1.25} \times 10^{-3}$$

$$= 45.26 \text{ kN}$$

From table 4.3

$$d = 20 \text{ mm}$$

$$d_o = 22 \text{ mm}$$

$$e = 23 \text{ mm}$$

Assume,

$$p = 50 \text{ mm}$$

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$$V_{pb} = 2.5 kbd t \frac{f_u}{Y_{mb}}$$

$$k_b = \text{less of } \left\{ \frac{e}{3d_o} = \frac{33 \text{ mm}}{3 \times 22 \text{ mm}} = 0.5 \right.$$

$$\frac{p}{3d_o} - 0.25 = \frac{50 \text{ mm}}{3 \times 22 \text{ mm}} - 0.25 = 0.51$$

$$\frac{f_{ub}}{f_u} = \frac{400 \text{ MPa}}{410 \text{ MPa}} = 0.98$$

1

So, $k_b = 0.5$

$$V_{pb} = 2.5 kbd t \frac{f_u}{Y_{mb}}$$

$$= 2.5 \times 0.5 \times 20 \text{ mm} \times 12 \text{ mm} \times \frac{40 \text{ MPa}}{1.25} \times 10^{-3}$$

$$= 98.4 \text{ kN}$$

∴ The strength of the bolt will be minimum in shear and bearing
i.e. 45.26.

b) For single cover butt joint ↗
 $t = 10 \text{ mm}$

The strength of bolt in single shear = 45.26 kN

The strength of bearing,

$$V_{pb} = 2.5 kbd t \frac{f_u}{Y_{mb}}$$

$$= 2.5 \times 0.5 \times 20 \text{ mm} \times 10 \text{ mm} \times \frac{410 \text{ MPa}}{1.25} \times 10^{-3}$$

$$= 82 \text{ kN}$$

So, strength of the bolt is 45.26 kN.

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$$t = 12 \text{ mm}$$

The strength of bolt in double shear,

$$V_{db} = 2 \times A_{ns} \frac{f_{ub}}{\sqrt{3} V_{mb}}$$

$$= 2 \times 245 \times \frac{400}{\sqrt{3} \times 1.25} \times 10^{-3}$$

$$= 90.52 \text{ kN}$$

The strength of bolt in bearing,

$$V_{pb} = 2.5 K_b d t \frac{f_y}{V_{mb}}$$

$$= 2.5 \times 0.5 \times 20 \times 12 \times \frac{410}{1.25} \times 10^{-3}$$

$$= 98.4 \text{ kN}$$

The strength of the bolt will be minimum of the strength in shear and bearing i.e. 90.52 kN.

Minimum Edge Distance of bolts

Nominal diameter of bolt (mm) (d)	Diameter of hole (mm) (d _o or d _h)	Distance of sheared on hand flame cut edge (mm)	Distance to machine flame cut, sawn or planed edge, (e) (mm)
12	13 and above	20	19
14	15	26	23
16	18	30	27
18	20	34	30
20	22	37	33
22	24	40	36
24	26	44	39
27	30	51	45
30	33	56	50
Over 33 mm	Bolt diameter + 3 mm	1.7 x hole diameter	1.5 x hole diameter

Q. A single-bolted double-cover butt joint is used to connect two plates which are 8 mm thick. Assuming 16 mm diameter bolts of grade 4.6 and cover plates to be 6 mm thick, calculate the strength and efficiency of the joint if 4 bolts are provided in the bolt line at a pitch of 45 mm.

Also determine the efficiency of the joint if two lines of bolts with two bolts in each line have been arranged to result in a double-bolted double cover butt joint.

Soln

Given data:-

For Fe 410 grade of steel,

$$f_u = 410 \text{ MPa}$$

For bolts of grade 4.6,

$$f_{ub} = 400 \text{ MPa}$$

For 16 mm dia bolt,

$$A_{nb} = 157 \text{ mm}^2$$

$$\gamma_{mb} = 1.25$$

$$\gamma_{ml} = 1.25$$

$$t = 8 \text{ mm}$$

Plate thickness (t) = 8 mm

Cover plate thickness (t_c) = 6 mm

Bolt diameter (d) = 16 mm

Bolt grade = 4.6

From Table 4.3:-

For 16 mm dia bolt,

$$A_{nb} = 157 \text{ mm}^2$$

$$\gamma_{mb} = 1.25$$

$$\gamma_{ml} = 1.25$$

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the strength of bolt in shear per pitch length,

$$V_{sb} = 2 \times A_{nb} \times \frac{f_{ub}}{\sqrt{3} \gamma_{mb}}$$

$$= 2 \times 157 \times \frac{400}{\sqrt{3} \times 1.25} \times 10^{-3}$$

$$= 58 \text{ kN}$$

$$t = 8 \text{ mm}$$

the strength of bolt in bearing per pitch length,

$$\Rightarrow V_{pb} = 2.5 k_b d t \frac{f_u}{\gamma_{mb}}$$

$$k_b = \text{least of } \left\{ \begin{array}{l} \frac{e}{3d_0} = \frac{3}{3 \times 18} = 0.55 \\ \frac{p}{3d_0} - 0.25 = \frac{45}{3 \times 18} - 0.25 = 0.52 \\ \frac{f_{ub}}{f_u} = \frac{400}{410} = 0.975 \\ 1 \end{array} \right.$$

$$k_b = 0.55$$

$$V_{pb} = 2.5 \times 0.55 \times 16 \times 8 \times \frac{400}{1.25} \times 10^{-3}$$
$$= 56.31 \text{ kN}$$

The net strength of plate per pitch length,

$$T_{nd} = 0.9 \frac{f_u}{\gamma_{m1}} A_n$$

$$T_{dn} = 0.9 \frac{f_u}{\gamma_{m1}} (p - d_h) t$$

From table 4.2,

$$T_{dn} = 0.9 \times \frac{410}{1.25} (45 - 18) \times 8 \times 10^{-3}$$

$$= 63.76 \text{ kN}$$

Strength of the solid plate per pitch length,

$$= 0.9 \frac{f_u}{\gamma_{m1}} p t$$

$$= 0.9 \times \frac{410}{1.25} \times 45 \times 8 \times 10^{-3}$$

$$= 106.27 \text{ kN}$$

the strength of the joint per pitch length = 56.31 kN

$$\text{Efficiency of the joint} = \frac{56.31}{106.27} \times 100$$
$$= 52.99\%$$

When the bolts are arranged in the rows the strength of the joint per pitch length on the basis of

a) Shear = $2 \times 58 = 116 \text{ kN}$

b) Bearing = 2×56.31
 $= 112.62 \text{ kN}$

c) Net tensile strength = 63.76 kN

So strength of the joint per pitch length = 63.76 kN

$$\text{Efficiency of the joint} = \frac{63.76}{106.27}$$
$$= 59.99\%$$

18/9/25

Simple welded Connection (chapter)

Introduction

- When two structural members are joined by means of welds, the connection is called a welded connection.
- Welded design offers the opportunity to achieve a more efficient use of materials.
- The speed of fabrication and erection helps compress production schedules.
- Welding saves weight and consequently cuts costs.
- No deductions are there for holes, thus the gross section is effective in carrying loads.
- Welded joints are better for fatigue loads, impact loads and vibrations.

Types

- 1) Fillet weld
- 2) Groove weld
- 3) Plug weld
- 4) Slot weld
- 5) Spot weld

Assumptions of loaded joint

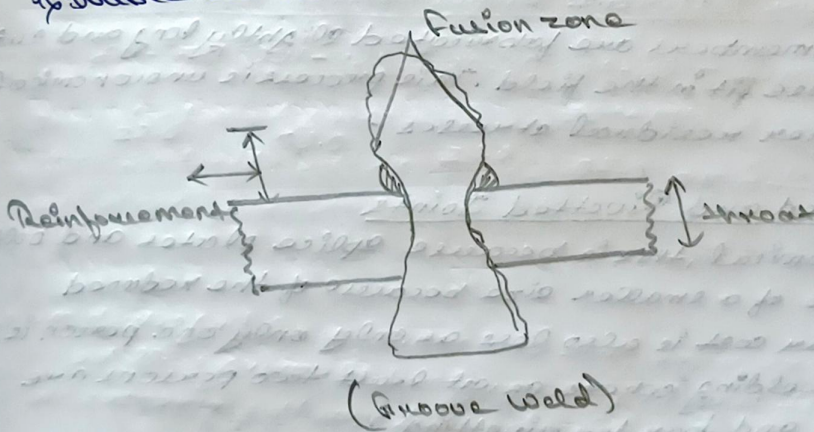
- The welding connection various parts are homogeneous, isotropic and elastic elements.
- The part connected by the weld are rigid and their force of deformation are neglected.
- Only stress due to external loads are consider.

Design of groove welds

- Groove and fillet weld are most frequently used.
- Groove welds are provided when the members to be joined are lined up.
- It requires edge preparation are costly.

Types of Groove weld

- 1/ Square
- 2/ Single VEE
- 3/ Double VEE
- 4/ Single V
- 5/ Double V
- 6/ Single Tee
- 7/ Double Tee
- 8/ Single be V
- 9/ Double be V



Design Strength

- The design strength of the groove weld in tension or compression is governed by yield.

$$T_{dw} = \frac{f_y A_w}{\gamma_{mw}}$$

where,

f_y = smaller of yield stress of the weld (f_{yw}) and the parent metal (f_y) in MPa.

L_w = effective length of the weld in mm

t_e = effective throat thickness of the weld in mm.

Partial safety factor
 = 1.25 for shop welding
 = 1.5 for site welding

- The design strength of the butt weld in shear is also governed by yield.

$$V_{dw} = \frac{f_y w_t L_w t_o}{\gamma_{mw}}$$

where,

$f_y w_t$ = smaller of shear stress of weld ($f_y w / \sqrt{3}$) and the parent metal ($f_y / \sqrt{3}$)

γ_{mw} = Partial safety factor as defined above.

$f_y w$ = yield stress of weld (MPa)

Design of Fillet Welds :-

- The fillet weld is done for members which overlap each other. For such joints the critical stress is shear stress.

Fillet Weld Vs Butt Weld

- 1) A fillet weld saves the operations of beveling and finishing the ends of members.
- 2) In case of butt weld, members are fabricated slightly long and cut exactly to have a close fit in the field. This process is uneconomical.
- 3) Butt welds have higher residual stresses.

Welded joints Vs Bolted and Rivetted Joints

- 1) Welded joints are economical, this is because splice plates and bolts/rivetted materials are of a smaller size because of the reduced connection length. Labour cost is also less as only one person is required to do the welding where as at least two persons are required for bolting and four for rivetting.
- 2) Welded structures are more rigid as compared to bolted/rivetted joints. In bolted/rivetted joints, cover plates, connecting angles etc. deflect along with the member during load transfer and make the joint more flexible.
- 3) Due to the fact that the strength of a welded joint is the same as that of the parent metals, even a smallest piece of the metal which otherwise is a scrap can be used, bringing overall economy.
- 4) With welding it has become possible to connect tubular sections, which are structurally very economical.

- 5) Due to the fusion of two metal pieces joined, a continuous structure is formed which gives a better architectural appearance than bolted/riveted joints.
- 6) Alterations can be done with ease expressed in case of welding as compared to bolting/riveting.
- 7) The process of welding is quicker in comparison to bolting/riveting.
- 8) The process of welding is silent, whereas in the case of riveting a lot of noise produced.
- 9) In welding less safety precautions are required for the public in the vicinity, whereas a hot rivet may fall and injure the persons working.
- 10) As steel plates, bolts/rivets etc are ^{not} required, the details and drawings of welded structures are easier and less time consuming.

20/9/25

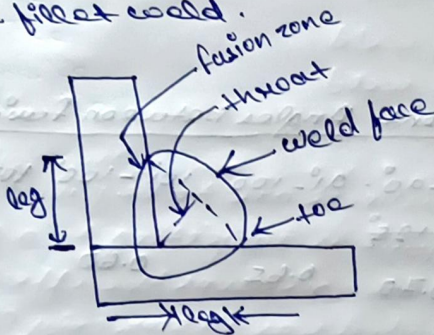
Design of fillet welds

Size (s) :-

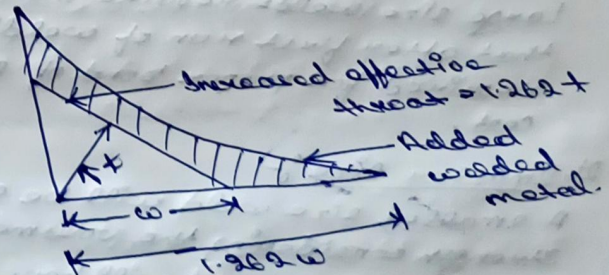
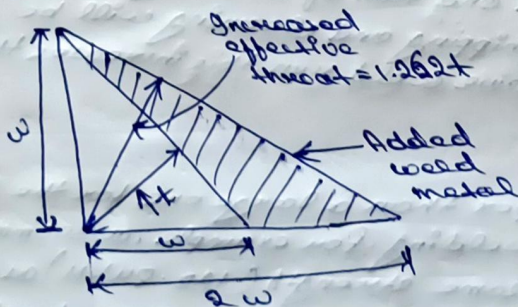
The minimum leg length of the weld.

Leg length :-

The leg length is the distance from the root to the toe of the toe of the fillet weld.



- It is measured by the largest right angle triangle which can be inscribed within the weld.



Size of weld(a) Maximum size of weld

It is obtained by subtracting 1.5 mm from the thickness of the thinner member to be joined.

(b) Minimum size of weld

The weld size should not be less than 2 mm

Table 5.4Minimum size of weldThickness of thinner memberMinimum size (mm)Over (mm)Upto and including (mm)

0

10

3

10

20

5

20

32

6

32

50

8 first run

10

Table 5.5Value of constant k for Different Angles between fusion faces

Angle between fusion faces — $60^\circ-90^\circ$ $91^\circ-100^\circ$ $101^\circ-106^\circ$ $107^\circ-113^\circ$ $114^\circ-120^\circ$ $121^\circ-125^\circ$

k

0.70

0.70

0.65

0.60

0.55

0.50

Minimum size1) Large size :-

Large size welds require more than one run of welding which means that after first run of welding chipping and cleaning will be required for proper bond of successive weld run. This increases the cost.

2) Smaller size :-

A smaller size weld will be cheaper than a large one for the same strength considering the volume of welding. For example, a 200 mm, 5 mm size fillet weld will have the same strength ($1.2 \times 24 \times 11$) as a 150 mm long and 10 mm size fillet weld. However the volume of weld metal for a 10 mm weld will be $\left[\frac{1}{2} \times 10^2 \times 150 = 7500 \text{ mm}^3\right]$

which is about twice that of 5 mm size weld,

$$\left[\frac{1}{2} \times 5^2 \times 300 = 3750 \text{ mm}^3\right]$$

Effective throat thickness

The shortest distance from the root of the fillet weld to the face of the diagrammatic weld (line joining to the e)

- Effective throat thickness should not be less than 2mm.
- It should not exceed $0.7t$ or $1.0t$

where,

t = thickness of thinner plate of elements being welded.

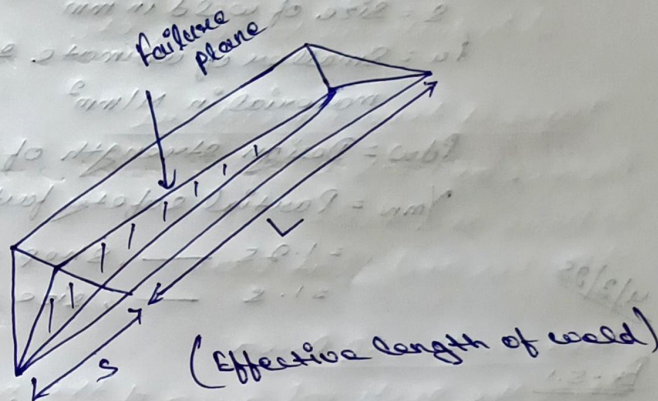
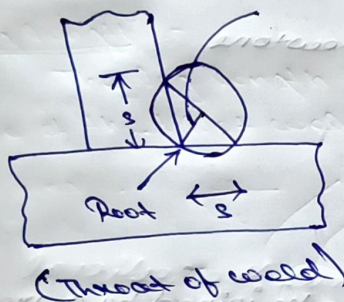
$$\begin{aligned}\text{Effective throat thickness} &= k \times \text{size of weld} \\ &= k \times e\end{aligned}$$

where,

e = size of weld in mm

k = constant

$$\begin{aligned}\text{Throat} &= ke \\ &= 0.707e\end{aligned}$$



* Fillet weld is not recommended if the angle between fusion force is less than 60° or more than 150°

For long joints the design capacity of weld is reduced by a factor,

$$\beta = 1.2 - \frac{0.2 l_j}{150 t} \leq 0.1$$

where,

l_j = length of joint in the ~~decrease~~ direction of force transfer.

t = throat size of the weld

Effective Area

It is equal to effective length of weld multiplied by effective throat thickness.

Design strength

Design strength of a fillet weld,

$$F_{wd} = \frac{F_{wn}}{\gamma_{mw}}$$

Run = nominal strength of fillet weld

$$= \frac{f_u}{\sqrt{3}}$$

The design strength of a fillet weld is based on its given by

$$P_{dw} = L_w \times t \times \frac{f_u}{\sqrt{3} \gamma_{mw}}$$

or,

$$= L_w \times t \times \frac{f_u}{\sqrt{3} \gamma_{mw}}$$

where,

L_w = effective length of weld in mm

t = throat thickness in mm

e = size of weld in mm

f_u = Smaller of ultimate strength of the weld and material in N/mm^2

P_{dw} = Design strength of weld in newtons

γ_{mw} = Partial safety factor

= 1.25 ———, shop weld

= 1.5 ———, site weld

4/2/25

Ex-5.1

Two plates of 16 mm and 14 mm thickness are to be joined by a groove weld as shown in fig. Ex-5.1 the joint is subjected to a factored tensile force of 430 kN. Due to some reasons the effective length of the weld that could be provided was 175 mm only. Check the safety of the joint if

a) Single V groove weld is provided.

b) Double V groove weld is provided

Assume the plates to be shop welded ($\gamma_{mw} = 1.25$)

Soln

Given:-

a) Single V groove weld:-

Tensile force = 430 kN

For Fe 410 grade of steel,

$f_y = 250 \text{ N/mm}^2$

$$= \frac{5}{8} \times 14 \text{ mm}$$

$$= 8.75 \text{ mm}$$

For shop weld,

$$V_{mw} = 1.25$$

Effective length of weld,

$$L_w = 175 \text{ mm}$$

Strength of the weld,

$$T_{dw} = L_w t_e \frac{f_y}{V_{mw}}$$

$$= 175 \times 8.15 \times \frac{250 \text{ MPa}}{1.25}$$

$$= 175 \times 8.15 \times \frac{250 \times 10^3 \text{ N/mm}^2}{1.25}$$

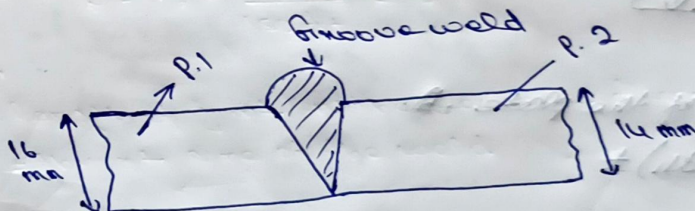
$$= 206.25 \text{ kN} < 430 \text{ kN thickness (t)} \\ \text{(not ok)}$$

b) Double-V groove weld :-

$$T_{dw} = L_w t_e \frac{f_y}{V_{mw}}$$

$$= 175 \times 14 \times \frac{250 \times 10^3 \text{ N/mm}^2}{1.25}$$

$$= 490 \text{ kN} > 430 \text{ (ok)}$$



TENSION MEMBERIntroduction

- A structural member subjected to two pulling tensile forces applied at its ends is called a tension member.
- The stress in an axial load, tension member can be determined by axial load with its cross-sectional area.

- e.g.

- e.g.

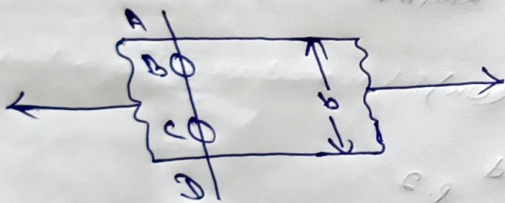
- 1) Trusses in building and bridge
- 2) Communication and satellite tower
- 3) Tie in lattice girder
- 4) Bracing system in multi-story building
- 5) Industrial building etc.

Types of tension member

- 1) Wire and cable
- 2) Bar and rod
- 3) Plate and flat bar

Net Sectional Area

- It is the sectional area of the member minus the sectional area of the maximum number of holes.



Net sectional area of the plate, A_n .

$$A_n = (b - ndh)t$$

where,

b = width of the plate

n = no. of bolts

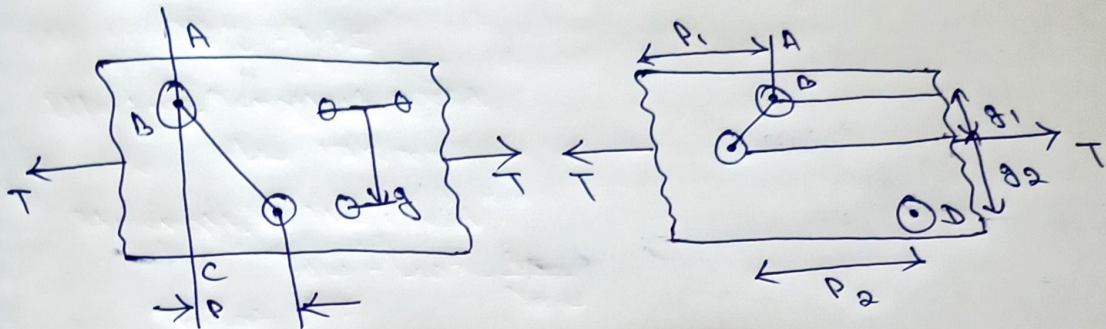
dh = dia of the bolt hole

t = thickness of plate

$$A_n = A_g$$

where,

A_g = Gross cross sectional area of the plate



$$A_n = A_g - \left[\text{sectional area of the hole} - \left(\frac{P_1^2 t}{4g_1} + \frac{P_2^2 t}{4g_2} \right) \right]$$

$$= bt - \left[ndht - \left(\frac{P_1^2 t}{4g_1} + \frac{P_2^2 t}{4g_2} \right) \right]$$

$$= bt - ndht + \frac{P_1^2 t}{4g_1} + \frac{P_2^2 t}{4g_2}$$

$$= \left(b - ndh + \frac{P_1^2}{4g_1} + \frac{P_2^2}{4g_2} \right) t$$

$$\text{If, } P_1 = P_2 = P$$

$$g_1 = g_2 = g$$

then,

$$A_n = \left(b - ndh + \frac{P^2}{4g} + \frac{P^2}{4g} \right) t$$

$$= \left(b - ndh + \frac{2P^2}{4g} \right) t$$

$$\Rightarrow A_n = \left(b - ndh + \frac{P^2}{2g} \right) t$$

where,

P = Pitch distance

g = Gauge distance